Car fleet synthesis for agent-based mobility models: a comparison of machine learning and discrete choice methods

Marjolaine Lannes, Nicolas Coulombel, Yelva Roustan









Literature review

ML vs DCM comparison in car ownership models

Table 1. Decision types and approches in car ownership modeling literature

Reference	Decision types					Approach		Model type		e
	Vehicle ownership	Car ownership	Car size	Fuel type	Car age	Actual	Forecast	DCM	ML	NN
Brownstone et al. (2000)				x		x	x	x		
Mohammadian and Miller (2002)			x				x	x		x
Whelan (2007)			x				x	x		x
Potoglou and Kanaroglou (2008b)		x				x		x		
Paredes et al. (2017)		x				x		x	x	
Kaewwichian et al. (2019)		x				x			x	x
Basu and Ferreira (2020)	x					x		x	x	
Dixon et al. (2021)		x				x	x		x	x
Zambang et al. (2021)	x					x		x	x	

Note. DCM: discrete choice model, ML: machine learning, NN: neural network









Methodology Problem statement



Figure : Vehicle fleet micro-representation based on households characteristics

Main objective : a microscopic and spatialized representation of vehicle fleet based on households characteristics of the synthetic population

Problem : which **models** and which **characteristics associated with households** would optimize the prediction of the vehicle fleet of a synthetic population ?

Al vs discrete choice methods







Methodology

Model types

Discrete choice method

Logistic regression

Supervised learning classification methods

Boosting methods

- Gradient boosting
- Ada Boost
- Light gradient boosting machine

Nearest neighbors

Discriminant analysis

- Linear discriminant analysis
- Quadratic discriminant
 analysis

Naive Bayes

Dummy classifier

Decision trees methods

- Decision tree classifier
- Extra Tree Classifier
- Random Forest Classifier

Support vector machines

Ridge classifier









Methodology Evaluation metrics

Indicators of performance	Formula	Interpretation
Accuracy score	$Acc = \frac{true \text{ predictions}}{\text{number of predictions}}$	Percentage of accurate predictions in the test sample, easy to interpret
Area under the curve (AUC) of the receiver operating characteristic (ROC)	$MAUC = \frac{2}{C(C-1)} \sum_{i < j} A(i,j)$	AUC converts ROC curve to a value in the range of [0.5, 1], where 1 means perfect classifier and 0.5 means no better than random classification. Multi-class AUC is average AUC of all pairs of classes.
F1-score	$F1 = \frac{2}{\frac{1}{precision} + \frac{1}{recall}}$	F1 is the harmonic mean of the precision and recall, value in range [0,1]. Preferable to accuracy in case of a large class imbalance.
Cohen's kappa (κ)	$\mathcal{K} = \frac{\mathrm{Acc} - P_e}{1 - P_e} \; ,$	Measure of agreement between observed and predicted or inferred classes for cases in a testing dataset, included in [-1,1]. If negative, a random classification is better.
Matthews Correlation Coefficient (MCC)	$MCC = \frac{TP \times TN - FP \times FN}{\sqrt{(TP + FP)(TP + FN)(TN + FP)(TN + FN)}}$	For multi-class : average MCC of all pairs of classes Measure of agreement, included in [-1,1]. If negative, a random classification is better











Data – Public transport modal share An indicator of regional accessibility

Public transport modal share : share of residents in a city taking public transports to go to their workplace

Modal share calculated from national census for professional mobility i.e. MobPro survey (INSEE)







rche 🔆 îlede France



Data – Variables

Variable	Description	Variable types
Age	Class of age of the oldest individual of the household	Socio-economic
Income *	Logarithm of the household's income	Socio-economic
N_workers	Number of employed actives in the household	Socio-economic
Household_type	Type of household (couple with / without children, single man/woman, monoparental family mother/father)	Socio-economic
Housing_type	Type of housing (flat, house, others)	Socio-economic
PT_share	Share of home city residents taking public transports to go to their workplace	Build environment
PT_share_work	Share of workplace city residents taking public transports to go to their workplace	Build environment
Commuting_distance *	Maximum commuting distance within household	Build environment
Parking	Presence of a private parking at home	Build environment
Parking_at_workplace	At least one person in the household has parking at their workplace	Build environment
N_cars	Number of cars owned by the household	Predicted variable
Fuel_type	Fuel type of the vehicle	Predicted variable
Euro_norm	European emission standard of the car, depending on the year the car was first put on the road	Predicted variable

* : with the indicator variable which values 1 if the household responded to the question, 0 otherwise







Fuel type results

Al vs discrete choice model performance

Model	Accuracy	AUC	Recall	Prec.	F1	Kappa	МСС	TT (Sec)
Ridge Classifier	0.587	0.000	0.325	0.582	0.582	0.184	0.185	0.004
Linear Discriminant Analysis	0.586	0.450	0.325	0.582	0.582	0.184	0.185	0.007
Logistic Regression	0.586	0.451	0.325	0.581	0.582	0.182	0.183	0.189
Gradient Boosting Classifier	0.568	0.432	0.335	0.568	0.568	0.154	0.154	0.271
Light Gradient Boosting Machine	0.562	0.414	0.341	0.560	0.560	0.139	0.139	0.086
Random Forest Classifier	0.562	0.405	0.341	0.559	0.560	0.137	0.138	0.097
Extra Trees Classifier	0.558	0.393	0.340	0.556	0.556	0.131	0.131	0.082
Decision Tree Classifier	0.538	0.381	0.354	0.539	0.537	0.097	0.097	0.007
K Neighbors Classifier	0.511	0.377	0.284	0.506	0.508	0.033	0.033	0.011
Dummy Classifier	0.504	0.350	0.275	0.254	0.338	0.000	0.000	0.004
Ada Boost Classifier	0.480	0.357	0.292	0.569	0.505	0.104	0.113	0.032
SVM - Linear Kernel	0.479	0.000	0.279	0.570	0.417	0.057	0.071	0.01
Naive Bayes	0.158	0.369	0.141	0.631	0.247	0.036	0.054	0.008
Quadratic Discriminant Analysis	0.082	0.354	0.214	0.461	0.127	0.007	0.012	0.004

· Ridge classifer slightly outperforms linear discriminant and logistic regression

- **F1-score** is closer to 1 than to 0 for most classifiers, indicating a quite satisfying prediction
- Cohen's kappa indicates a slight, nearly fair for gradient boosting classifier, agreement : $\kappa \in [0; 0, 20]$
- Matthews Correlation Coefficient (MCC) also reaches +0,185 > 0 for gradient boosting, attesting a slight agreement







Fuel type results Feature importance (ridge classifier)



Fuel type results Logistic regression coefficients



ParisTech

Results synthesis

Decision type	Best model type	Model performance	Most important variables
Households car ownership	Gradient boosting	F1-score : 0,763 Cohen kappa : substantial, agreement ($\kappa = 0,629$) <i>MCC</i> = +0,630 : strong positive relationship	Absence of parking at home Housing : flat Public transport share home Income Commuting distance Household : couple with child
Cars fuel type	Ridge classifier	F1-score : 0,582 Cohen kappa : slight agreement ($\kappa = 0,184$) MCC = +0,185 : slight agreement	Household : single woman Commuting distance indicator Age (>75) Household : couple with child Income
Cars emission standard	Linear discriminant analysis	F1-score : 0,282 Cohen kappa : slight agreement ($\kappa = 0,053$) MCC = +0,054 : slight, negligible relationship	Income No worker Commuting distance indicator One worker Household : single woman/man









Discussion

Results analysis

- Car ownership: results consistent with litterature (accessibility and built environment variables)
- Fuel type: sociodemographic variables (energy cost)
- Car age: income and commuting distance

Contribution of machine learning

- For all decision levels, machine learning outperforms DCM
- MCC as evaluation metric: imbalanced dataset

Outlook

- More data for better performance? (especially for underrepresented classes)
- Comparison with *Parc Auto* survey









Outlook

- Integration of the model in MATSim for the calculation of emissions and exposures at the household level
- PhD topic : Modeling the exposure to air pollution in Île-de-France region: uncertainty analysis with a multi-agent approach



Ville Mobilité Transport Réseau de recherche Qualité de l'air en Ile-de-France



Outlook

- Integration of the model in MATSim for the calculation of emissions and exposures at the household level
- PhD topic : Modeling the exposure to air pollution in Île-de-France region: uncertainty analysis with a multi-agent approach





Thank you for your attention





Bibliography

- Basu, R. and Ferreira, J.: Understanding household vehicle ownership in Singapore through a comparison of econometric and machine learning models, Transportation Research Procedia, 48, 1674–1693, https://doi.org/10.1016/j.trpro.2020.08.207, 2020.
- Brownstone, D., Bunch, D. S., and Train, K.: Joint mixed logit models of stated and revealed preferences for alternative-fuel vehicles, Transportation Research Part B: Methodological, 34, 315–338, 2000.
- Dixon, J., Koukoura, S., Brand, C., Morgan, M., and Bell, K.: Spatially Disaggregated Car Ownership Prediction Using Deep Neural Networks, Future Transportation, 1, 113–133, https://doi.org/10.3390/futuretransp1010008, number: 1 Publisher: Multidisciplinary Digital Publishing Institute, 2021.
- Kaewwichian, P., Tanwanichkul, L., and Pitaksringkarn, J.: Car ownership demand modeling using machine learning: decision trees and neural networks, International Journal of GEOMATE, 17, 219–230, https://doi.org/https://doi.org/10.21660/2019.62.94618, 2019.
- Mohammadian, A. and Miller, E. J.: Nested Logit Models and Artificial Neural Networks for Predicting Household Automobile Choices: Comparison of Performance, Transportation Research Record, 1807, 92–100, https://doi.org/10.3141/1807-12, publisher: SAGE Publications Inc, 2002.
- Paredes, M., Hemberg, E., O'Reilly, U.-M., and Zegras, C.: Machine learning or discrete choice models for car ownership demand estimation and prediction?, in: 2017 5th IEEE International Conference on Models and Technologies for Intelligent Transportation Systems (MT-ITS), pp. 780–785, https://doi.org/10.1109/MTITS.2017.8005618, 2017.
- Potoglou, D. and Kanaroglou, P. S.: Modelling car ownership in urban areas: a case study of Hamilton, Canada, Journal of Transport Geography, 16, 42–54, https://doi.org/10.1016/j.jtrangeo.2007.01.006, 2008.
- Whelan, G.: Modelling car ownership in Great Britain, Transportation Research Part A: Policy and Practice, 41, 205–219, https://doi.org/10.1016/j.tra.2006.09.013, 2007.
- Zambang, M. A. M., Jiang, H., and Wahab, L.: Modeling vehicle ownership with machine learning techniques in the Greater Tamale Area, Ghana, PLOS ONE, 16, e0246044, https://doi.org/10.1371/journal.pone.0246044, publisher: Public Library of Science, 2021.







Appendix





Context Air quality challenge : mobility & emissions model

Context

- Public policies to improve air quality focus on vehicle fleet regulation, low emission zones
- Need to represent vehicle types in mobility models to precise and spacialize emissions by road trafic
- **Agent-based models** (ABM) for mobility modelling : require a synthetic population



Main objective : a microscopic and spacialized representation of vehicle fleet based on households characteristics of the synthetic population







Literature review

Disaggregated car ownership choice modeling

Discrete choice modeling (DCM) in transportation research :

- 1973 : development of conditional multinomial logit (MNL) by McFadden
- 1975 : first application of MNL to car ownership by Lerman and Ben-Akiva
- 1980 : joint car ownership and mode choice DCM by Train
- 1985 : publication of « Discrete Choice Analysis: Theory and Application to Travel Demand », written by Lerman et. al.

1994 : first study comparing mobility surveys and public census data in car ownership modeling by Purvis

Ville Mobilité Transpor







Data – GTS 2018





100

80

mother Couple with child Single father Others

single mother

40

Age

60

Car ownership results

Al vs discrete choice model performance

Model	Accuracy	AUC	Recall	Prec.	F1	Карра	MCC	TT (Sec)
Gradient Boosting Classifier	0.766	0.897	0.766	0.763	0.763	0.629	0.630	0.201
Logistic Regression	0.755	0.893	0.759	0.753	0.752	0.614	0.616	0.450
Random Forest Classifier	0.752	0.892	0.747	0.749	0.749	0.605	0.606	0.077
Light Gradient Boosting Machine	0.751	0.888	0.749	0.750	0.749	0.605	0.605	0.049
Linear Discriminant Analysis	0.747	0.887	0.768	0.753	0.741	0.610	0.618	0.005
Extra Trees Classifier	0.746	0.879	0.745	0.743	0.743	0.597	0.598	0.082
Ridge Classifier	0.732	0.000	0.736	0.734	0.722	0.580	0.588	0.003
Decision Tree Classifier	0.688	0.743	0.685	0.690	0.688	0.504	0.505	0.014
Ada Boost Classifier	0.663	0.840	0.722	0.708	0.656	0.500	0.525	0.034
Naive Bayes	0.649	0.831	0.715	0.754	0.647	0.491	0.538	0.003
SVM - Linear Kernel	0.646	0.000	0.657	0.680	0.616	0.452	0.481	0.010
K Neighbors Classifier	0.554	0.693	0.521	0.549	0.546	0.271	0.274	0.013
Dummy Classifier	0.491	0.500	0.333	0.241	0.323	0.000	0.000	0.003
Quadratic Discriminant Analysis	0.381	0.557	0.430	0.502	0.349	0.113	0.148	0.006

- Gradient boosting slightly outperforms logistic regression and other artificial intelligence models
- **F1-score** is largely closer to 1 than to 0, indicating a satisfying prediction
- Cohen's kappa indicates a substantial agreement for gradient boosting: $\kappa \in [0,61; 0,80]$
- Matthews Correlation Coefficient (MCC) reaches +0,606 for gradient boosting indicating a strong positive relationship







Car ownership results

Confusion matrix for gradient boosting classifier



*** île**de**France**

Ville Mobilité Transport





Car ownership results

Feature importance (gradient boosting classifier)



Car ownership results Logistic regression coefficients



Fuel type results Confusion matrix for ridge classifier



en Ile-de-France



ParisTech

Emission standards results

Al vs discrete choice model performance

Model	Accuracy	AUC	Recall	Prec.	F1	Карра	MCC	TT (Sec)
Linear Discriminant Analysis	0.282	0.553	0.204	0.268	0.265	0.053	0.054	0.007
Logistic Regression	0.281	0.548	0.197	0.260	0.258	0.047	0.048	0.234
Ridge Classifier	0.282	0.000	0.193	0.253	0.258	0.046	0.047	0.004
Ada Boost Classifier	0.274	0.541	0.200	0.259	0.251	0.042	0.044	0.034
Light Gradient Boosting Machine	0.256	0.550	0.190	0.242	0.247	0.036	0.036	0.121
Gradient Boosting Classifier	0.261	0.538	0.183	0.238	0.244	0.031	0.032	0.405
Extra Trees Classifier	0.245	0.526	0.184	0.239	0.240	0.027	0.027	0.086
Random Forest Classifier	0.251	0.537	0.179	0.236	0.242	0.027	0.027	0.099
K Neighbors Classifier	0.240	0.513	0.181	0.238	0.236	0.023	0.023	0.014
Naive Bayes	0.099	0.523	0.186	0.244	0.107	0.014	0.023	0.008
Decision Tree Classifier	0.227	0.511	0.177	0.232	0.228	0.018	0.018	0.006
Quadratic Discriminant Analysis	0.174	0.503	0.179	0.239	0.147	0.006	0.006	0.004
SVM - Linear Kernel	0.216	0.000	0.178	0.146	0.120	0.003	0.004	0.015
Dummy Classifier	0.265	0.500	0.167	0.070	0.111	0.000	0.000	0.003

Linear discriminant analysis slightly outperforms logistic regression

- F1-score is closer to 0, indicating an unsatisfying prediction
- Cohen's kappa indicates a slight agreement : *κ* ∈ [0,10 ; 0,20], except for SVM, dummy and naive Bayes models (to exclude)
- Matthews Correlation Coefficient (MCC) also indicates a negligible relationship, slightly better than random



<mark>Laboratoire</mark>-Ville Mobilité Transport







Emission standards results

Confusion matrix for linear discriminent analysis



Emission standards results

Feature importance (linear discriminent analysis)



Emission standards results Logistic regression coefficients

