

# Exercise 7

## Bytecode Verification and Generics

### self-study exercise sheet

**NOTE:** There will not be a regular exercise session on 6 November, and you will take the midterm exam instead. Therefore this exercise sheet will not be discussed in an exercise session. We publish it now together with the solution to allow you to better prepare for the midterm. If you have any questions regarding this sheet, please consult your assistant.

### Task 1

The method `f` of class `E` has the following signature:

```
void f();
```

and one local variable `v`. The maximal stack size is equal to 1.

It has the following body:

```
0: iconst 5
1: istore 1
2: aload 0
3: astore 1
4: iload 1
5: iconst 1
6: iadd
7: istore 1
8: return
```

Can the provided byte code be verified? If so then verify it, otherwise explain which line of the code causes the problem and why.

— solution —

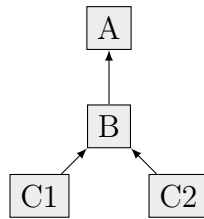
In the following, we try to verify the bytecode. `T` is an uninitialized register. A state is represented by a pair  $(S, R)$  where  $S$  describes the contents of the state and  $R$  describes the contents of registers.

```
// ([],[E,T]) -- initial state
iconst 5
// ([int],[E,T])
istore 1
// ([], [E,int])
aload 0
// ([E], [E,int])
astore 1
// ([], [E,E])
iload 1
// ERROR!
...
```

The error happens because `iload 1` expects that the local variable has integer type, but its type is `E`.

## Task 2

Consider the following type hierarchy:



Suppose that the method `f` of class `E` has the following signature:

```
A f(boolean b1, boolean b2);
```

and there are three local variables `x`, `y`, `z`. It is known that the initial state is:

```
([], [E,boolean,boolean,C1,C2,A])
```

The maximal stack size is equal to 1.

The method `f` has the following body:

```
0: iload 1
1: ifeq 22
4: iload 2
5: ifeq 12
8: aload 3
9: goto 14
12: aload 4
14: astore 3
15: aload 5
17: astore 4
19: goto 0
22: aload 3
23: areturn
```

Note: In this example, `ifeq x` pops an integer from the stack and jumps to line `x` if the integer is equal to zero.

**A)** Verify that the program is type safe.

— solution —

Here the initial state is `([], [E,b,b,C1,C2,A])`. We denote the type `boolean` as `b` for convenience (in reality the Java bytecode verifier views it as an integer).

We show the solution following the convention of Lecture 4, Slide 21. To each command we dedicate an input and an output column. A command may have multiple inputs and outputs, corresponding to the different iterations of the algorithm. You may also want to see an animated solution of this task, published separately.

		IN	OUT
0	iload 1	([], [E,b,b,C1,C2,A]) ([], [E,b,b,B,A,A]) ([], [E,b,b,A,A,A])	([b], [E,b,b,C1,C2,A]) ([b], [E,b,b,B,A,A]) ([b], [E,b,b,A,A,A])
1	ifeq 22	([b], [E,b,b,C1,C2,A]) ([b], [E,b,b,B,A,A]) ([b], [E,b,b,A,A,A])	([], [E,b,b,C1,C2,A]) ([], [E,b,b,B,A,A]) ([], [E,b,b,A,A,A])
4	iload 2	([], [E,b,b,C1,C2,A]) ([], [E,b,b,B,A,A]) ([], [E,b,b,A,A,A])	([b], [E,b,b,C1,C2,A]) ([b], [E,b,b,B,A,A]) ([b], [E,b,b,A,A,A])
5	ifeq 12	([b], [E,b,b,C1,C2,A]) ([b], [E,b,b,B,A,A]) ([b], [E,b,b,A,A,A])	([], [E,b,b,C1,C2,A]) ([], [E,b,b,B,A,A]) ([], [E,b,b,A,A,A])
8	aload 3	([], [E,b,b,C1,C2,A]) ([], [E,b,b,B,A,A]) ([], [E,b,b,A,A,A])	([C1], [E,b,b,C1,C2,A]) ([B], [E,b,b,B,A,A]) ([A], [E,b,b,A,A,A])
9	goto 14	([C1], [E,b,b,C1,C2,A]) ([B], [E,b,b,B,A,A]) ([A], [E,b,b,A,A,A])	([C1], [E,b,b,C1,C2,A]) ([B], [E,b,b,B,A,A]) ([A], [E,b,b,A,A,A])
12	aload 4	([], [E,b,b,C1,C2,A]) ([], [E,b,b,B,A,A]) ([], [E,b,b,A,A,A])	([C2], [E,b,b,C1,C2,A]) ([A], [E,b,b,B,A,A]) ([A], [E,b,b,A,A,A])
14	astore 3	([C1], [E,b,b,C1,C2,A]) ([B], [E,b,b,C1,C2,A]) ([B], [E,b,b,B,A,A]) ([A], [E,b,b,B,A,A]) ([A], [E,b,b,A,A,A])	- ([], [E,b,b,B,C2,A]) - ([], [E,b,b,A,A,A]) ([], [E,b,b,A,A,A])
15	aload 5	([], [E,b,b,B,C2,A]) ([], [E,b,b,A,A,A])	([A], [E,b,b,B,C2,A]) ([A], [E,b,b,A,A,A])
17	astore 4	([A], [E,b,b,B,C2,A]) ([A], [E,b,b,A,A,A])	([], [E,b,b,B,A,A]) ([], [E,b,b,A,A,A])
19	goto 0	([], [E,b,b,B,A,A]) ([], [E,b,b,A,A,A])	([], [E,b,b,B,A,A]) ([], [E,b,b,A,A,A])
22	aload 3	([], [E,b,b,C1,C2,A]) ([], [E,b,b,B,A,A]) ([], [E,b,b,A,A,A])	- - ([A], [E,b,b,A,A,A])
23	areturn	([C1], [E,b,b,C1,C2,A]) ([B], [E,b,b,B,A,A]) ([A], [E,b,b,A,A,A])	- - ([], [E,b,b,A,A,A])

**B)** Provide the minimal type information that enables verification of the bytecode without a fixpoint computation.

— solution —

In the following code, we mark the types that are given by the user, and those inferred by the type checker.

```
// given: ([], [E,b,b,A,A,A])
0: iload 1
// ([b], [E,b,b,A,A,A])
1: ifeq 22
```

```

    // ([], [E,b,b,A,A,A])
4: iload 2
    // [b], [E,b,b,A,A,A]
5: ifeq 12
    // ([], [E,b,b,A,A,A])
8: aload 3
    // ([A], [E,b,b,A,A,A])
9: goto 14

    // ([], [E,b,b,A,A,A])
12: aload 4
    // given: ([A], [E,b,b,A,A,A])
14: astore 3
    // ([], [E,b,b,A,A,A])
15: aload 5
    // ([A], [E,b,b,A,A,A])
17: astore 4
    // ([], [E,b,b,A,A,A])
19: goto 0
    // ([], [E,b,b,A,A,A])
22: aload 3
    // ([A], [E,b,b,A,A,A])
23: areturn
    // ([], [E,b,b,A,A,A])

```

The requirement to have type information at all basic blocks is a simplification that makes it easier to determine where the compiler should output the information. Note that some basic blocks have only a single preceding instruction, but determining this statically could be hard. Such basic blocks do not in theory need type information. Only basic blocks that are also join points definitely need type information. In our example, instructions 4, 8, 12 and 22 are indeed the beginnings of basic blocks, but there is exactly one path to enter these blocks and therefore type information is not really needed since this information will be identical to the *out*-state of the single preceding instruction.

### Task 3

Consider the following Java code:

```

interface IFace {
    void m();
}
class Cl1 implements IFace {
    public void m() { System.out.println("Cl1.m"); }
}
class Cl2 implements IFace {
    public void m() { System.out.println("Cl2.m"); }
}
public class Test1 {
    public static void main( String[] args ) {
        xxx(true);
        xxx(false);
    }
    public static void xxx( boolean param ) {
        IFace iface = null;
        if( param ) { iface = new Cl1(); }
        else { iface = new Cl2(); }
        iface.m();
    }
}

```

}

**A)** What type will be calculated for the variable `iface` of the method `xxx` during the bytecode verification?

— solution —

Because the inference algorithm doesn't take interfaces into consideration, the calculated type for the variable `iface` is `Object`.

**B)** When can we decide that `iface.m()` is safe to call? During bytecode verification, or execution?

— solution —

Because the inferred type of the `iface` is `Object` the decision can be made only during the execution.

**C)** What if `IFace` was a class instead of an interface? What if it was an abstract class?

— solution —

In both cases the inferred type of the `iface` is `IFace`. The decision about the safety of the call can be made during bytecode verification.

## Task 4

The bytecode type inference algorithm rejects a verified program if there are different stack sizes for input values of a join point.

**A)** Provide a bytecode program that is rejected because of this limitation but that does not cause runtime errors.

— solution —

```
0 : aload 0
1 : iconst 1
2 : ifne 4
3 : aload 0
4 : astore 1
```

Note: `ifne` jumps to the given index if the integer value at the top of the stack is not equal to zero. It pops the value at the top of the stack.

There are two possibilities for the stack size after executing this program. In any of the two cases, the height of the stack at point 4 is at least 1, and there will be surely a reference value at the top of the stack.

**B)** Is it possible to construct a bytecode verification algorithm that avoids this limitation? If yes, then provide an updated algorithm. If no, then show that it can't be done.

— solution —

We distinguish between two different cases.

1. If the stack sizes are statically known we can construct such an algorithm. The update is as follows: when joining stacks of different sizes, pick the smallest one, but carry as extra information the size of the largest one to be used when checking for overflow. Note that if we just picked the smaller one and used that, we would not prevent stack overflows at runtime.  
If we just picked the largest one and made the “extra” values into dummy values by giving them the “top” type, we might not prevent underflows when using instructions such as `pop()`.
2. In general it is not possible to implement an algorithm that can deal with stack sizes which could vary at run-time. For example if we push elements on top of the stack in a loop, then the verifier will have no way of deciding what an upper bound for the size is. Conversely for loops which pop elements from the stack the verifier won't be able to deduce a lower bound for the stack size. These situations can easily result in over/underflows and should be rejected.

C) How serious is this restriction from a pragmatic perspective?

— solution —

This limitation is not essential. If there are two states  $\{[head1, x], [head2]\}$  where `head1` and `head2` are stacks of the same size, then any following code cannot access `x` and it would have been possible to remove `x` already during bytecode generation. This is indeed what the Java compiler does. Consider the following Java code:

```
public int bar() { return 42;}
public int foo(int x) {
    if (x==0)    bar();
    return x;
}
```

If `bar` is called then it will put 42 on the stack, but this value is not actually needed for the final `return` instruction. The Java compiler would emit as many `pop` instructions as necessary to remove unneeded stack elements and make sure that all paths that reach `return` have the same stack length. Here is the bytecode that corresponds to the `foo` method:

```
0: iload_1
1: ifne          9
4: aload_0
5: invokevirtual bar // Call to bar(), puts an int on the stack
8: pop           // Pop the stack to remove the unnecessary int
9: iload_1       // Here we get equal stack sizes from both paths
10: ireturn
```

## Task 5

Consider the following Scala code:

```
class A[-T]
class B[... T] {
    def m(in : A[T]) : Int = {...}
}
```

We want to annotate the generic type parameter of `B`. If we use a covariant or a contravariant annotation for the generic type parameter of `B`, what would that annotation be? Why? Justify

your answer with an example.

— solution —

The only annotation that may be used here is + (covariant). Subtypes of B may override the m method. Due to contravariance of method arguments, valid subtypes of B may use a supertype of A[T] for the argument in. Due to the declared contravariance of A[T], supertypes of A[T] are classes A[X] where  $X <: T$ . Thus,  $B[X] <: B[T]$  if  $X <: T$  and we must use a covariant annotation:  $B[+T]$ .

If we use contravariance, then the following code will break:

```
class A[-T] {
  def len(t:T) : Int = 1
}

class AStr extends A[String] {
  override def len(s:String) : Int = { s.length() }
}

class B[-T]
{
  def m(x:A[T]) : Int = 2
  // The compiler gives this error message on the previous line:
  // contravariant type T occurs in covariant position in type
  // A[T] of value x
}

class BAnyRef extends B[AnyRef]
{
  override def m(x:A[AnyRef]) : Int = { x.len(new Integer(3)) } }

// Client
class F {
  def f() {
    val a = new AStr
    val b = new BAnyRef
    b.m(a) // If the code would compile, here we would try to
           // call length() on an Integer object
  }
}
```

## Task 6

Consider the following Scala classes:

```
class A
class B extends A
class P1[+T]
class P2[T <: A]
```

What are the possible instantiations of P1 and P2? What is the difference between P1[A] and P2[A] from the perspective of a client? Provide an example to show which class is more restrictive.

— solution —

Class P1 can be instantiated with any type, while P2 has to be instantiated with subtypes of A.

```
val x : P1[AnyRef] //correct
val y : P2[AnyRef] //wrong: AnyRef is not a subtype of A
```

Furthermore, class P1 is covariant in its argument:

```
val x : P1[A]=new P1[B] //correct  
val y : P2[A]=new P2[B] //wrong: found P2[B], required P2[A]
```