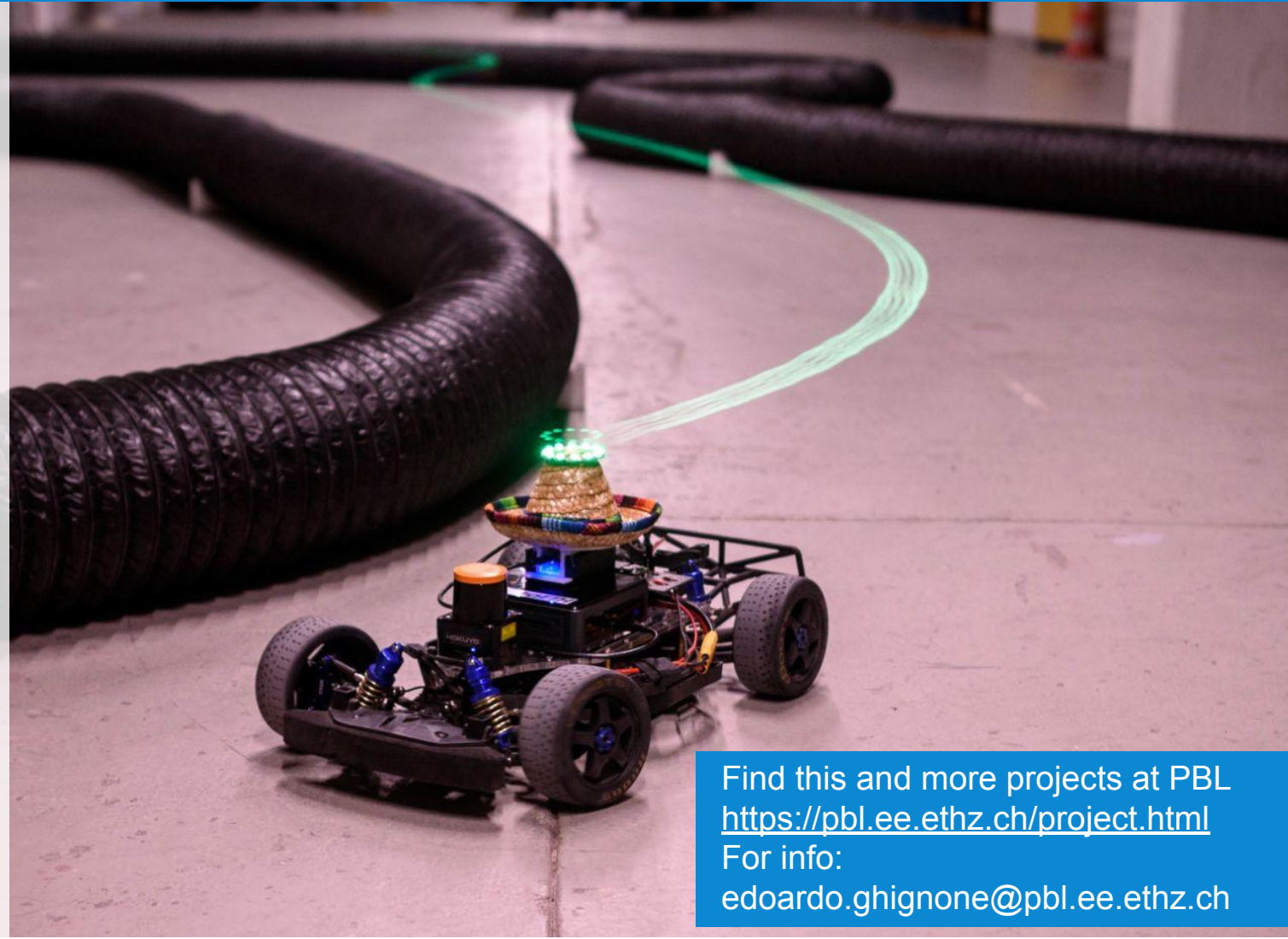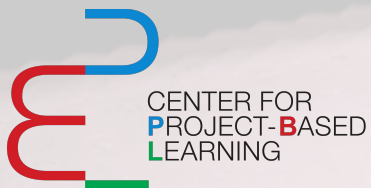# PBL Flagship Project
ForzaETH - Autonomous Racing
Bachelor/Semester/Master Thesis

Develop and implement novel robotic algorithms in the context of autonomous racing for your master/semester/bachelor thesis.

You have the opportunity, to test your work on multiple physical robotic systems. We are looking to improve our racing stack in the following areas:

- Computer Vision
- Controls
- Planning
- Perception
- State Estimation
- Sensor Technology

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LEARNING

ForzaETH

Find this and more projects at PBL
https://pbl.ee.ethz.ch/project.html
For info:
edoardo.ghignone@pbl.ee.ethz.ch