Improve Robotic Sailing!

With a Bachelor/Semester Thesis at PBL

Are you curious about the particular requirements for robotic sailing boats?

Would you like to work with embedded systems under space and low-power constraints?

Do you want to set up telemetry links or access and design ultra low power sensors?

We are looking to improve our boat in the following areas:

- Telemetry link to base station
- Optimize Sensors and design new ones (e.g. wind speed)
- Path planning and Control



