

## Lecture 10: (Chap. 4, cont.)

We will now begin the discussion of stochastic integrals.

We assume that

(4.19)  $(\Omega, \mathcal{G}, (\mathcal{G}_t)_{t \geq 0}, \mathbb{P})$  is a filtered probability space satisfying the usual conditions (4.5), (4.6),

(4.20)  $X_t, t \geq 0$ , is a continuous square integrable  $(\mathcal{G}_t)$ -martingale,

(4.21)  $X_t^2 - t, t \geq 0$ , is a  $(\mathcal{G}_t)$ -martingale.

A "concrete example of this situation occurs for instance in (4.10), (4.17), (4.18), when considering  $(C, \mathbb{F}, (\mathbb{F}_t)_{t \geq 0}, W_0)$  and the canonical process  $X_t, t \geq 0$ .

Remark:

We will later see, of Chapter 5, that when  $M_t, t \geq 0$ , is a continuous square integrable martingale on  $(\Omega, \mathcal{G}, (\mathcal{G}_t)_{t \geq 0}, \mathbb{P})$ , as in (4.19), (i.e. for each  $t \geq 0$ ,  $E[M_t^2] < \infty$ ), one can construct a process  $\langle M \rangle_t, t \geq 0$ , such that

(4.22)  $t \rightarrow \langle M \rangle_t(\omega)$  is non-decreasing continuous, for each  $\omega \in \Omega$ ,

(4.23)  $\langle M \rangle_0 = 0$ ,

(4.24)  $\langle M \rangle_t, t \geq 0$ , is  $(\mathcal{G}_t)$ -adapted, integrable,

(4.25)  $M_t^2 - \langle M \rangle_t, t \geq 0$ , is a  $(\mathcal{G}_t)$ -martingale.

Moreover  $\langle M \rangle_t$  is essentially unique, (i.e. two such processes agree for all  $t \geq 0$ , except maybe on a negligible set of  $\omega \in \Omega$ ), and it is called the "quadratic variation process". The terminology stems from the fact that for  $t \geq 0$ ,

$$\sum_{\frac{k+1}{2^n} \leq t} \left( M_{\frac{k+1}{2^n}} - M_{\frac{k}{2^n}} \right)^2 \xrightarrow{\pi \rightarrow \infty} \langle M \rangle_t \quad \text{in } \mathbb{P}\text{-probability,}$$

see Karatzas-Shreve, section 1.5.

We are going to define the integral  $\int_0^t H_\Delta dX_\Delta$  for some suitable basic integrands, for which the definition is "natural", and then we will use an isometry property to extend the class of processes we integrate. Later we will further extend the class of integrands by a so-called "localization argument".

Our building blocks are the basic processes:

$$(4.26) \quad H_\Delta(\omega) = C(\omega) 1_{\{a < s \leq b\}}, \quad s \geq 0, \omega \in \Omega, \text{ with } C \in b\mathcal{G}_{a, \text{pos}, s, b}.$$

For such an  $H$  as in (4.26), we define:

$$(4.27) \quad \int_0^\infty H_\Delta dX_\Delta \stackrel{\text{def}}{=} C(\omega) (X_b(\omega) - X_a(\omega)) \in L^2(\mathcal{P}).$$

The restriction  $C(\omega) \in b\mathcal{G}_a$  is not a priori natural. It is motivated by the fact that if we define

$$(4.28) \quad (H \cdot X)_t \stackrel{\text{def}}{=} \int_0^t H_\Delta 1_{\{0 \leq \Delta \leq s\}} dX_\Delta \stackrel{(4.27)}{=} C(\omega) (X_{b \wedge t} - X_{a \wedge t})$$

↑ also denoted  $\int_0^t H_\Delta dX_\Delta$

we have the

Proposition:

$$(4.29) \quad M_t = (H \cdot X)_t \text{ is a continuous square integrable } (\mathcal{G}_t)\text{-martingale.}$$

Proof:

$$\begin{aligned} (H \cdot X)_t &= C(\omega) (X_{b \wedge t} - X_{a \wedge t}) \\ &= 0, \quad \text{if } 0 \leq t \leq a, \\ &= C(X_b - X_a), \quad \text{if } a \leq t \leq b, \\ &= C(X_b - X_a), \quad \text{if } b \leq t \leq \infty, \end{aligned}$$

clearly defines a continuous adapted process which is square integrable. Considering the case  $a \leq s < t \leq b$ , (the other cases are simpler), we see that

$$\begin{aligned} E[M_t - M_s | \mathcal{G}_s] &= E[C(X_b - X_a) | \mathcal{G}_s] \stackrel{\text{P.a.s.}}{=} C E[X_b - X_s | \mathcal{G}_s] \\ &= 0. \end{aligned}$$

Our claim follows.  $\square$

The next step is the following

Proposition:

If  $H, K$  are basic processes, then

$$(4.30) \quad E[(H \cdot X)_t (K \cdot X)_t] = E\left[\int_0^t H_s(\omega) K_s(\omega) ds\right], \text{ for } 0 \leq t \leq \infty.$$

Proof:

It suffices to consider the case  $t = \infty$ , because

$$(H \cdot X)_t = (H 1_{[0,t]} \cdot X)_\infty.$$

It also suffices to check (4.30) when  $(a, b] = (c, d]$  or  $(a, b] \ll (c, d]$ ,

(i.e.  $a \leq b < c \leq d$ ), and  $H = C 1_{(a, b]}$ ,  $K = D 1_{(c, d]}$ .

Indeed one makes repeated use of identities such as

$$(4.31) \quad \text{for } 0 \leq \alpha \leq \beta \leq \gamma, \quad H = C 1_{(\alpha, \gamma]}, \quad H^1 = C 1_{(\alpha, \beta]}, \quad H^2 = C 1_{(\beta, \gamma]} \\ \int_0^\infty H_\Delta dX_\Delta = \int_0^\infty H^1_\Delta dX_\Delta + \int_0^\infty H^2_\Delta dX_\Delta$$

We will thus only need to check (4.30) in two cases:

- case  $(a, b] = (c, d]$ :

$$(4.32) \quad E[(H \cdot X)_\infty (K \cdot X)_\infty] = E\left[\int_a^b CD (X_b - X_a)^2\right] = \\ E\left[CD E[(X_b - X_a)^2 | \mathcal{G}_a]\right].$$

Note that:

$$(4.33) \quad E[(X_b - X_a)^2 | \mathcal{G}_a] = E[X_b^2 - 2X_b X_a + X_a^2 | \mathcal{G}_a] = \\ E[X_b^2 | \mathcal{G}_a] - 2X_a E[X_b | \mathcal{G}_a] + X_a^2 \stackrel{(4.20)}{=} E[X_b^2 | \mathcal{G}_a] - X_a^2 = \\ E[X_b^2 - b | \mathcal{G}_a] + b \cdot X_a^2 \stackrel{(4.21)}{=} X_a^2 - a + b - X_a^2 = b - a.$$

Thus coming back to (4.32) we have shown that

$$E[(H \cdot X)_\infty (K \cdot X)_\infty] = E[CD(b-a)] = E\left[\int_a^b H_s(\omega) K_s(\omega) ds\right], \\ \text{i.e. (4.30) holds.}$$

- case  $(a, b] \ll (c, d]$ :

$$E[(H \cdot X)_\infty (K \cdot X)_\infty] = E[(H \cdot X)_\infty E[(K \cdot X)_\infty | \mathcal{G}_b]] \\ \stackrel{\mathcal{G}_b\text{-meas}}{=} \stackrel{(4.29)}{=} E[(H \cdot X)_\infty (K \cdot X)_b] = 0.$$

Analogously we have

$$E\left[\int_0^\infty H(s, \omega) K(s, \omega) ds\right] = 0, \text{ and (4.30) holds.}$$

□

Remark:

If we replace  $(X_t)_{t \geq 0}$  satisfying (4.20), (4.21), with  $(M_t)_{t \geq 0}$ , a continuous square integrable martingale, and defines for basic processes  $H_\Delta(\omega) = C(\omega) 1_{[a, b]}$ , with  $C \in \mathcal{G}_a$ ,

$$(4.34) \int_0^\infty H_\Delta dM_\Delta = C(M_b - M_a), \text{ and } \int_0^t H_\Delta dM_\Delta = \int_0^\infty H_\Delta 1_{[0, t]}(s) dM_\Delta, \text{ } 0 \leq t \leq \infty,$$

then (4.30) is replaced by

$$(4.35) E[(H \cdot M)_t (K \cdot M)_t] = E\left[\int_0^t H_\Delta(\omega) K_\Delta(\omega) d\langle M \rangle_\Delta(\omega)\right],$$

with  $\langle M \rangle$  the quadratic variation of  $M$ , and  $(H \cdot M)_t$  defined as in (4.28) with  $M$  replacing  $X$ .  $\square$

We now define the class  $\Lambda_1$  of simple processes:

$$(4.36) \Lambda_1 = \{ H_\Delta(\omega) = H_\Delta^1(\omega) + \dots + H_\Delta^p(\omega), H^i \text{ are basic} \}.$$

Proposition and definition:

$$(4.37) \text{ For } H \in \Lambda_1, \int_0^\infty H_\Delta dX_\Delta \stackrel{\text{def}}{=} \sum_{i=1}^p \int_0^\infty H_\Delta^i dX_\Delta, \text{ is well defined.}$$

Proof:

The only point to check is that when  $H^1, \dots, H^p$  are basic processes such that  $H^1 + \dots + H^p = 0$ , then  $\sum_{i=1}^p \int_0^\infty H_\Delta^i dX_\Delta = 0$ .

Making repeated use of (4.31) and

$$(4.38) H = C 1_{[a, b]}, K = D 1_{[a, b]} \text{ basic processes, then } \int_0^\infty H_\Delta dX_\Delta + \int_0^\infty K_\Delta dX_\Delta = \int_0^\infty L_\Delta dX_\Delta, \text{ with } L = (C+D) 1_{[a, b]} \text{ basic process,}$$

we can assume that

$$H^i = C_i 1_{I^i}, 1 \leq i \leq p, \text{ with } I^i \cap I^j = \emptyset, \text{ when } i \neq j. \text{ In this case}$$

$$H^1 + \dots + H^p = 0 \text{ implies } H^1 = H^2 = \dots = H^p = 0, \text{ and hence}$$

$$\sum_{i=1}^p \int_0^\infty H_\Delta^i dX_\Delta = 0. \text{ Our claim is thus proved. } \square$$

As a consequence of (4.29) and (4.37) we see that for  $H, K \in \Lambda_1$ ,

$$(4.39) \int_0^t H_\Delta dX_\Delta \stackrel{\text{def}}{=} \int_0^\infty H_\Delta 1_{[0, t]}(s) dX_\Delta \text{ is a continuous square integrable martingale,}$$

and  $E\left[\int_0^\infty H_\Delta dX_\Delta \int_0^\infty K_\Delta dX_\Delta\right] = E\left[\int_0^\infty H_\Delta K_\Delta ds\right].$

Remark:

In the case of a general continuous square-integrable  $(\mathcal{G}_t)$ -martingale  $M_t, t \geq 0$ , in place of  $X_t, t \geq 0$ , we can use the same construction as above. The role of  $ds$  is simply replaced by  $d\langle M \rangle_s(\omega)$  so that for  $H, K \in \Lambda_1$ , we have

$$(4.40) \quad \mathbb{E} \left[ \int_0^\infty H_s dM_s \int_0^\infty K_s dM_s \right] = \mathbb{E} \left[ \int_0^\infty H_s(\omega) K_s(\omega) d\langle M \rangle_s(\omega) \right]. \quad \square$$

As a result of (4.39), we see that

$$(4.41) \quad K \in \Lambda_1 \rightarrow \int_0^\infty K_s dX_s \in L^2(\Omega, \mathcal{G}, P) \text{ is an isometry,}$$

if  $\Lambda_2$  is viewed as a subspace of  $L^2(\Omega \times \mathbb{R}_+, \mathcal{G} \otimes \mathcal{B}(\mathbb{R}_+), dP \otimes ds)$ .

Note that  $\Lambda_1$  is in general not dense in  $L^2(\Omega \times \mathbb{R}_+, \mathcal{G} \otimes \mathcal{B}(\mathbb{R}_+), dP \otimes ds)$ , since all  $K$  in  $\Lambda_1$  are progressively measurable processes. We hence consider

$$(4.42) \quad \mathcal{P} = \text{the } \sigma\text{-algebra of progressively measurable sets in } \Omega \times \mathbb{R}_+, \text{ (i.e. of } A \in \mathcal{G} \otimes \mathcal{B}(\mathbb{R}_+) \text{ such that for all } t \geq 0, A \cap (\Omega \times [0, t]) \in \mathcal{G}_t \otimes \mathcal{B}([0, t])).$$

Remark:

A process  $Z(s, \omega)$  on  $(\Omega, \mathcal{G}, (\mathcal{G}_t)_{t \geq 0}, P)$  is progressively measurable in the sense of the definition below (2.61) exactly when

$$(4.43) \quad (\Omega \times \mathbb{R}_+, \mathcal{P}) \xrightarrow{\cong} (\mathbb{R}^d, \mathcal{B}(\mathbb{R}^d)) \text{ is measurable.} \quad \square$$

We then define:

$$(4.44) \quad \Lambda_2 = L^2(\Omega \times \mathbb{R}_+, \mathcal{P}, dP ds),$$

the set of progressively measurable processes  $H(s, \omega)$  for which  $\mathbb{E} \left[ \int_0^\infty H^2(s, \omega) ds \right] < \infty$ . The interest of this definition comes from the next:

Proposition:

(4.45)  $\Lambda_1$  is a dense subset of  $\Lambda_2$  for the  $L^2(\Omega \times \mathbb{R}_+, \mathcal{P}, dPds)$ -distance,

(4.46)  $H \rightarrow \int_0^\infty H_s dX_s$  extends uniquely into an isometry from  $\Lambda_2$  into  $L^2(\Omega, \mathcal{G}, P)$ .

Proof:

In view of (4.41) we see that (4.46) immediately follows from (4.45).

The proof of (4.45) will in fact rely on a lemma, which is more general than what is needed to prove (4.45), but applies as well to the subsequent discussion of stochastic integrals with respect to continuous square integrable martingales. The non-decreasing process  $t \rightarrow A_t(\omega)$  in the next lemma plays the role of  $t \rightarrow \langle M \rangle_t(\omega)$ , cf. (4.22).

Lemma:

Suppose that  $A_t, t \geq 0$ , is a continuous  $(\mathcal{G}_t)$ -adapted process, non-decreasing in  $t$ , with  $A_0 = 0$ , and  $E[A_t] < \infty$ , for every  $t \geq 0$ , then

(4.47)  $\Lambda_1$  is a dense subset of  $L^2(\Omega \times \mathbb{R}_+, \mathcal{P}, dP dA_s)$  for the  $L^2(dP dA_s)$ -distance.

(The  $\sigma$ -finite measure  $d\mu = dP dA_s$  is defined via

$$\mu(B) = \int_{\Omega} \left( \int_0^\infty 1_B(\omega, u) dA_u(\omega) \right) dP(\omega),$$

for  $B \in \mathcal{G} \otimes \mathcal{B}(\mathbb{R}_+) \supset \mathcal{P}$ ).

With the above lemma, (4.45) clearly follows.

There remains to prove the lemma.