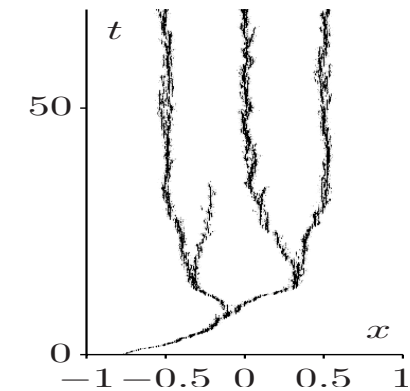
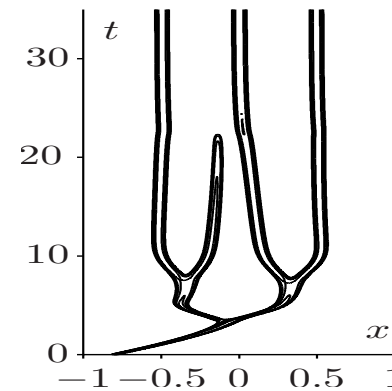
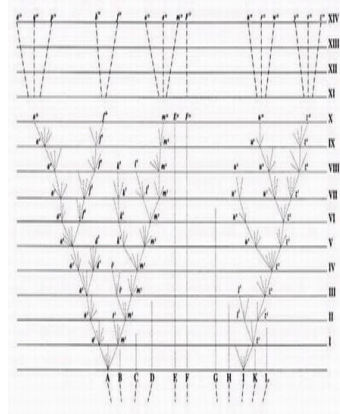
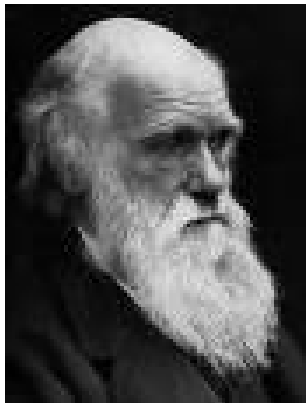




Adaptation, selection, mutation : a mathematical view of evolution

Benoît Perthame, METE 2018



Population formalism

$$\underbrace{\frac{\partial}{\partial t} n(x, t)}_{\text{variation of number of individuals}} = \underbrace{\int b(y) M(x, y) n(y, t) dy}_{\text{birth with mutations}} + n(x, t) \underbrace{R(x, I(t))}_{\text{growth rate}}$$

- $n(x, t)$ = number of individuals with trait x
- x = phenotypical trait
- $I(t) = (I_1(t), \dots, I_J(t))$ = environmental unknowns
- $R(x, I)$ of Lotka-Volterra type, can be negative
- Standard : Calsina, Cuadrado, Desvilletes, Raoul, Jabin, Mirrahimi, ...

Population formalism

$$\underbrace{\frac{\partial}{\partial t} n(x, t)}_{\text{variation of number of individuals}} = \underbrace{\int b(y) M(x, y) n(y, t) dy}_{\text{birth with mutations}} + n(x, t) \underbrace{R(x, I(t))}_{\text{growth rate}}$$

- $n(x, t)$ = number of individuals with trait x
- x = phenotypical trait
- $I(t) = (I_1(t), \dots, I_J(t))$ = environmental unknowns
- $R(x, I)$ of Lotka-Volterra type, can be negative
- interplay between population and environment



Population formalism

A variant is

$$\underbrace{\frac{\partial}{\partial t} n(x, t)}_{\text{variation of number of individuals}} = \underbrace{\Delta n(y, t)}_{\text{neutral mutations}} + n(x, t) \underbrace{R(x, I(t))}_{\text{growth rate}}$$



Motivation

The variable x can be

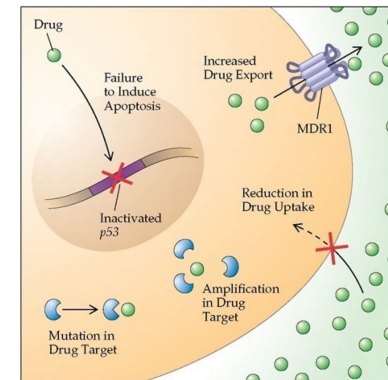
- Size of the adult individuals (adaptation to foraging)
- Cannibalism rate (and evolutionary suicide)
- Cooperative behaviour
- Dispersal rate

Motivation



But adaptation can be seen on shorter times scales

- Resistance of tumor cells to chemotherapy
- Resistance to insecticides



Rescaling



$$\varepsilon \frac{\partial}{\partial t} n_\varepsilon(x, t) = \int b(y) M_\varepsilon(x, y) n_\varepsilon(y, t) dy + n_\varepsilon(x, t) R(x, I_\varepsilon(t)),$$

- $M_\varepsilon(x, y)$ means mutations are rare/have small effect

Rescaling

$$\varepsilon \frac{\partial}{\partial t} n_\varepsilon(x, t) = \int b(y) M_\varepsilon(x, y) n_\varepsilon(y, t) dy + n_\varepsilon(x, t) R(x, I_\varepsilon(t)),$$

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- $\varepsilon \frac{\partial}{\partial t} n_\varepsilon(x, t)$ means we consider a long time scale

Rescaling

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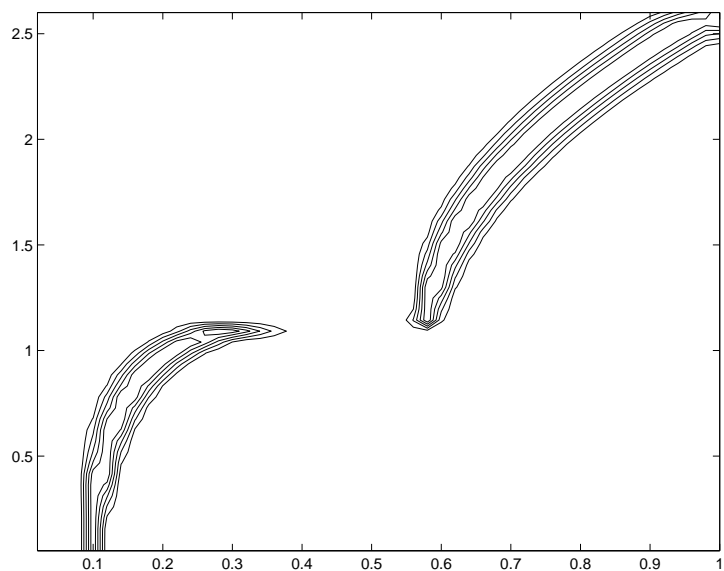
- $M_\varepsilon(x, y)$ means mutations are rare/have small effect
- $\varepsilon \frac{\partial}{\partial t} n_\varepsilon(x, t)$ means we consider a long time scale
- $M_\varepsilon(x, y) = \frac{1}{\varepsilon^d} M\left(\frac{x-y}{\varepsilon}\right)$

Rescaling

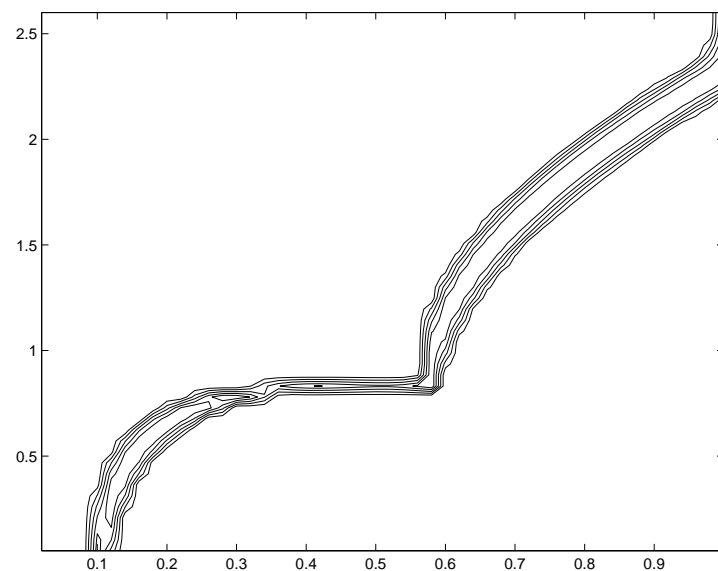
$$\varepsilon \frac{\partial}{\partial t} n_\varepsilon(x, t) = \int b(y) M_\varepsilon(x, y) n_\varepsilon(y, t) dy + n_\varepsilon(x, t) R(x, I_\varepsilon(t)),$$

- $M_\varepsilon(x, y)$ means mutations are rare/have small effect
- $\varepsilon \frac{\partial}{\partial t} n_\varepsilon(x, t)$ means we consider a long time scale
- $M_\varepsilon(x, y) = \frac{1}{\varepsilon^d} M\left(\frac{x-y}{\varepsilon}\right)$
- Concentrations occur $n_\varepsilon(x, t) \approx e^{-|x-\bar{x}(t)|^2/\varepsilon}$

Examples of behaviors

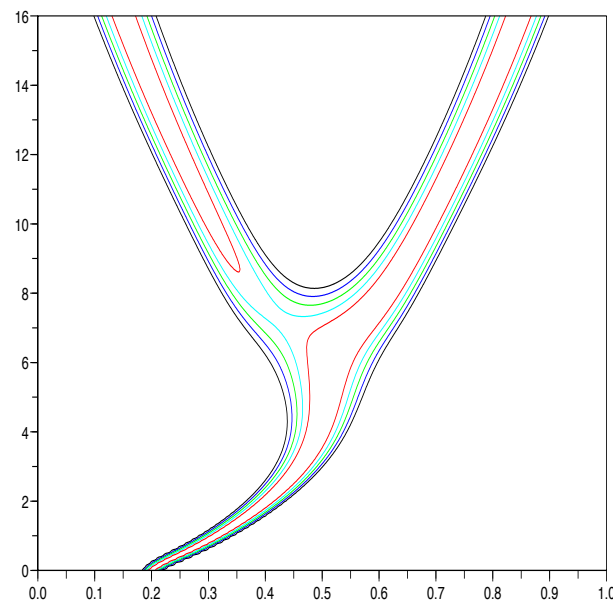
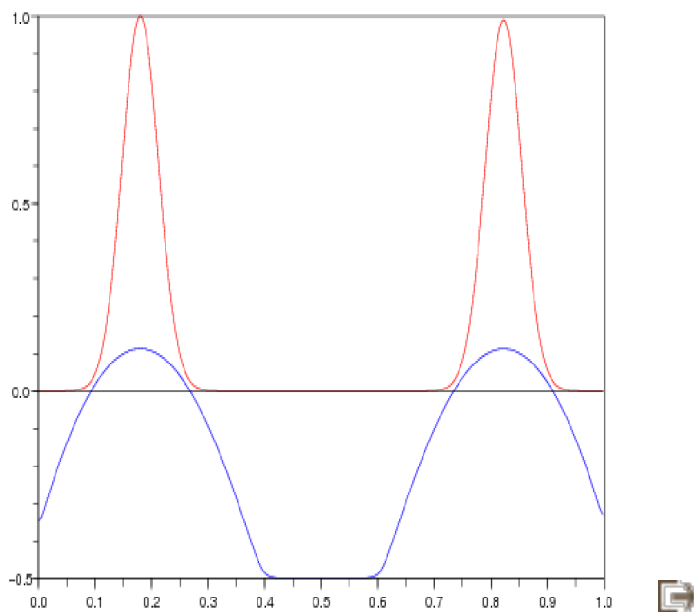


Direct simulation (1500 points)



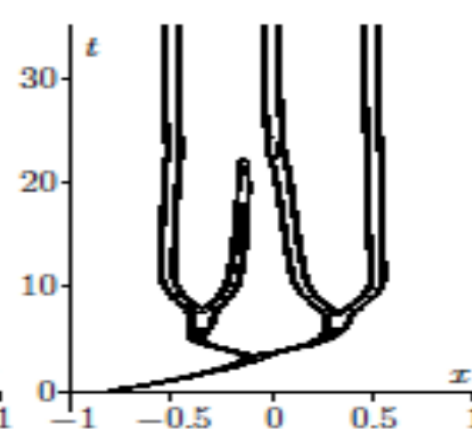
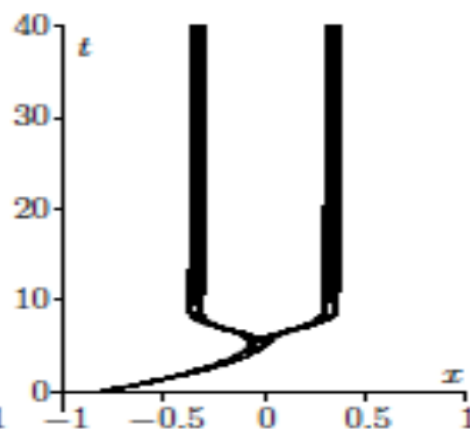
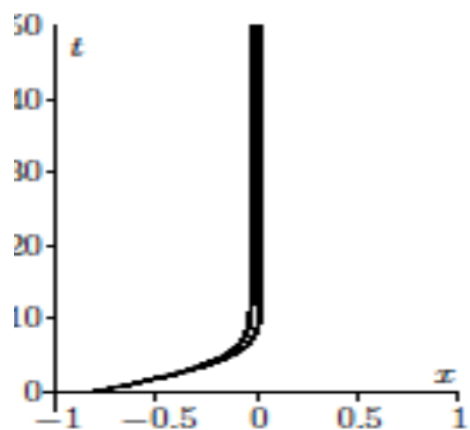
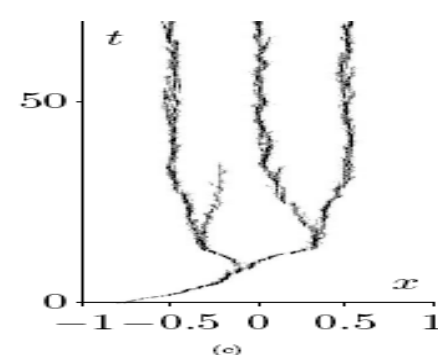
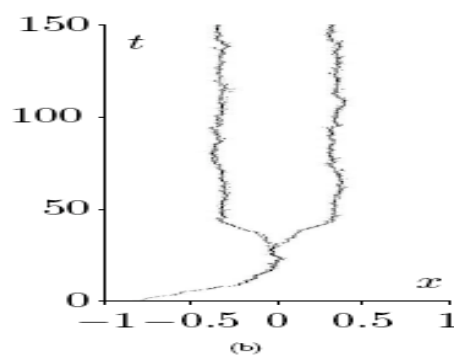
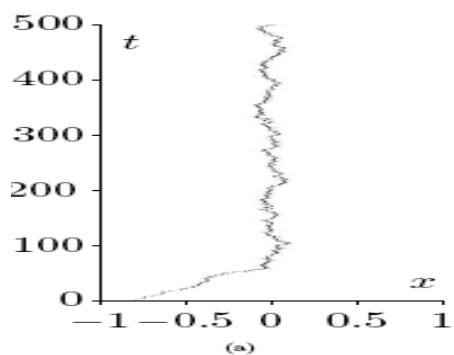
H.-J. solution (200 points)

Examples of behaviors



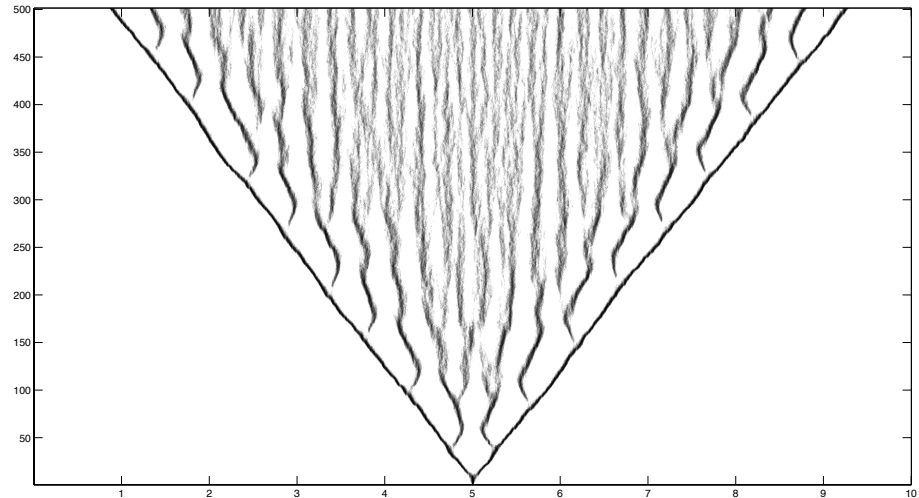
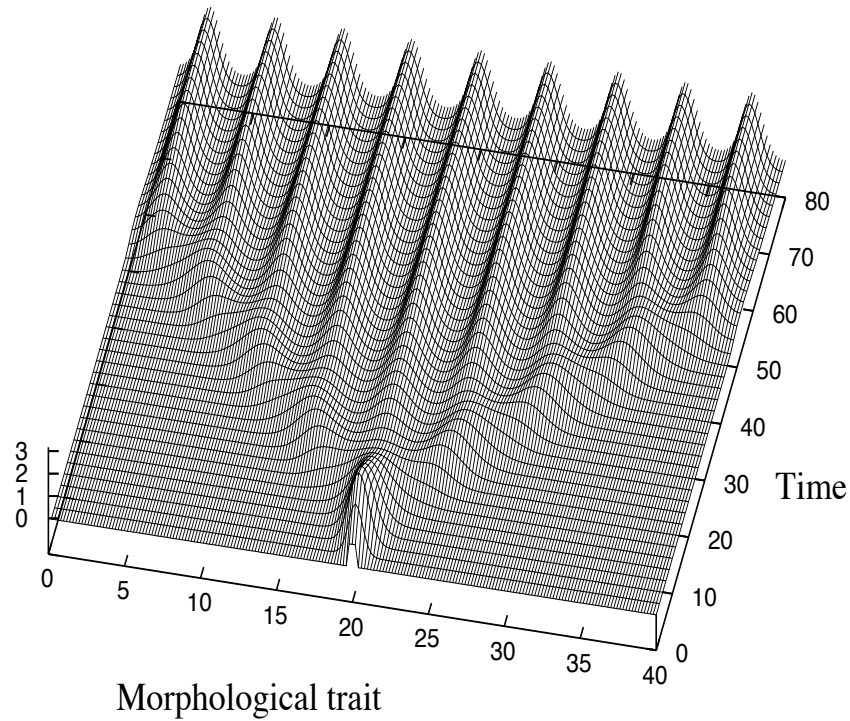
Branching can occur for more general right hand sides (convolution)

Examples of behaviors



Branching for a Gaussian convolution

Examples of behaviors



Branching for a non-Gaussian convolution

Rescaling

$$\varepsilon \frac{\partial}{\partial t} n_\varepsilon(x, t) = \int b(y) M_\varepsilon(x, y) n_\varepsilon(y, t) dy + n_\varepsilon(x, t) R(x, I_\varepsilon(t)),$$

- $M_\varepsilon(x, y)$ means mutations are rare/have small effect
- $\varepsilon \frac{\partial}{\partial t} n_\varepsilon(x, t)$ means we consider a long time scale
- Simple case $I_\varepsilon(t)$ is reduced to the knowledge of

$$\rho_\varepsilon(t) = \int_{\mathbb{R}^d} n_\varepsilon(x, t) dx$$

Concentration phenomena

$$\begin{cases} \varepsilon \frac{\partial}{\partial t} n_\varepsilon(x, t) - \varepsilon^2 \Delta n_\varepsilon = n_\varepsilon(x, t) R(x, \varrho_\varepsilon(t)), & x \in \mathbb{R}, \\ \varrho_\varepsilon(t) = \int_{\mathbb{R}^d} n_\varepsilon(x, t) dx. \end{cases}$$

- $\exists \varrho_M > 0$ s.t. $\max_x R(x, \varrho_M) = 0$
- $R_\varrho < 0$ ■ $R_x > 0$

Theorem (d=1, monotone) For well-prepared initial data, we have

$$n_\varepsilon(x, t) \xrightarrow{\varepsilon_k \rightarrow 0} \bar{\varrho}(t) \delta(x = \bar{x}(t)), \quad \bar{x}(t), \bar{\varrho}(t) \in BV_{\text{loc}}(0, \infty)$$

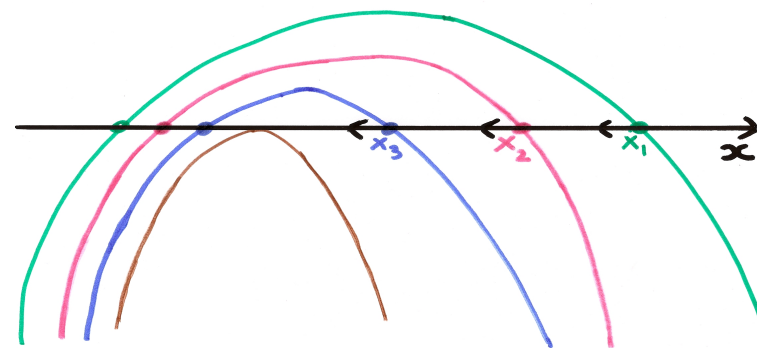
$$R(\bar{x}(t), \bar{\varrho}(t)) = 0 \quad \text{for a.e. } t > 0$$

$$\text{as } t \rightarrow \infty \quad R(\bar{x}_\infty, \bar{\varrho}_\infty) = 0 = \max_x R(x, \bar{\varrho}_\infty)$$

Concentration phenomena, $d \geq 1$

$$\begin{cases} \varepsilon \frac{\partial}{\partial t} n_\varepsilon(x, t) - \varepsilon^2 \Delta n_\varepsilon = n_\varepsilon(x, t) R(x, \varrho_\varepsilon(t)), & x \in \mathbb{R}^d \\ \varrho_\varepsilon(t) = \int_{\mathbb{R}^d} n_\varepsilon(x, t) dx. \end{cases}$$

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Theorem (Any d , concave) For well-prepared initial data, we have

$$n_\varepsilon(x, t) \longrightarrow \bar{\varrho}(t) \delta(x = \bar{x}(t)), \quad \bar{x}(t), \bar{\varrho}(t) \in C^1([0, \infty))$$

$$R(\bar{x}(t), \bar{\varrho}(t)) = 0 \quad \text{for all } t > 0$$

$$\text{as } t \rightarrow \infty \quad R(\bar{x}_\infty, \bar{\varrho}_\infty) = 0 = \min_\varrho \max_x R(x, \varrho)$$

Concentration phenomena



Why is mathematics interesting ?

- Nonlocal nonlinearity drastically changes the picture
- Control in L^1 only
- Constrained Hamilton-Jacobi eq.
- Is there a simple rule for the dynamics of $\bar{x}(t)$?

Related approaches

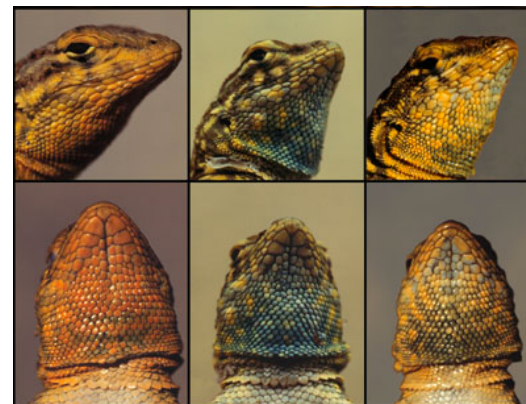
- **Evolutionary game theory**

Blue (stronger),

Orange (middle size),

Yellow (smaller)

compensate by mating **strategies**



from B. Sinervo. <http://bio.research.ucsc.edu/barrylab>

NATURE VOL. 246 NOVEMBER 2 1973

The Logic of Animal Conflict

J. MAYNARD SMITH

School of Biological Sciences, University of Sussex, Falmer, Sussex BN1 9QG

G. R. PRICE

Galton Laboratory, University College London, 4 Stephenson Way, London NW1 2HE

J. Hofbauer- M. Nowak- K. Sigmund

Related approaches

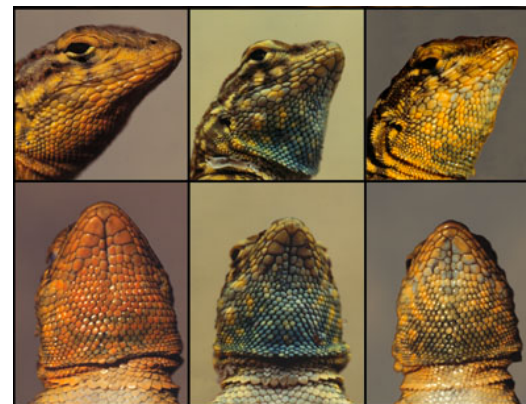
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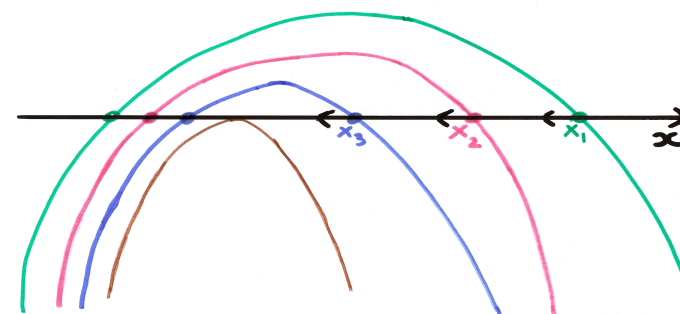


from B. Sinervo. <http://bio.research.ucsc.edu/barrylab>

The relation can be seen by

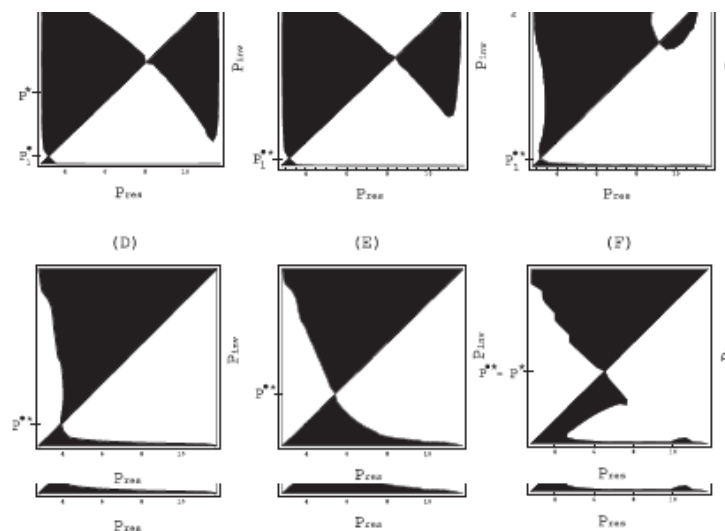
$$\max_{\mathcal{S}} R(x, \bar{\rho}_{\infty}) = 0 = R(\bar{x}_{\infty}, \bar{\rho}_{\infty})$$

$$\min_{\varrho} \max_{\mathcal{S}} R(x, \varrho) = 0 = R(\bar{x}_{\infty}, \bar{\rho}_{\infty})$$



Related approaches

- **Dynamical systems**



H. Metz, S. Geritz, G. Meszena,
S. Kisdi, **O. Diekmann**

Can a mutant invade the resident population ?

Related approaches

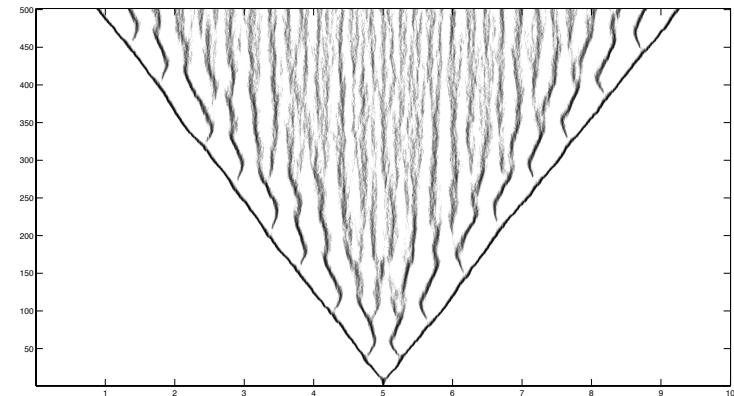


- Stochastic models, Individual Based Models : N individuals, rescale mutation, birth, death rates

U. Dieckmann-R. Law, R. Ferriere

S. Billard, N. Champagnat

S. Méléard, V. C Tran



Related approaches

- Stochastic models, Individual Based Models : N individuals,
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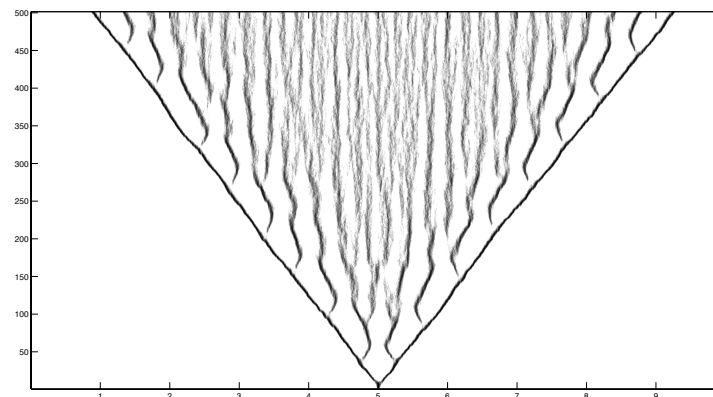
R. Ferriere, N. Champagnat

S. Méléard, V. C Tran

As $N \rightarrow \infty$, they establish both

$$\varepsilon \frac{\partial}{\partial t} n_\varepsilon(t, x) - \varepsilon^2 \Delta n_\varepsilon = n_\varepsilon(t, x) R(x, \varrho_\varepsilon(t))$$

$$\varepsilon \frac{\partial}{\partial t} n_\varepsilon(x, t) = \int b(y) \frac{1}{\varepsilon^d} M\left(\frac{x-y}{\varepsilon}\right) n_\varepsilon(y, t) dy + n_\varepsilon(x, t) R(x, I_\varepsilon(t)),$$



Asymptotics with mutations

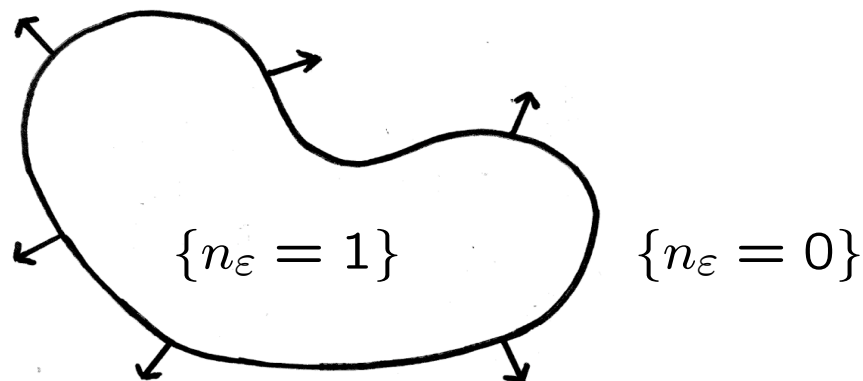


$$\begin{cases} \varepsilon \frac{\partial}{\partial t} n_\varepsilon(t, x) - \varepsilon^2 \Delta n_\varepsilon = n_\varepsilon(t, x) R(x, \varrho_\varepsilon(t)), \\ \varrho_\varepsilon(t) = \int_{\mathbb{R}^d} n_\varepsilon(t, x) dx. \end{cases}$$

Asymptotics with mutations

This is not far from Fisher/KPP equation for invasion fronts/chemical reaction

$$\varepsilon \frac{\partial}{\partial t} n_\varepsilon(t, x) - \varepsilon^2 \Delta n_\varepsilon = n_\varepsilon(t, x) (1 - n_\varepsilon(t, x)),$$



WKB, large deviations, level sets, geometric motion

G. Barles, L. C. Evans, W. Fleming, P. E. Souganidis, Mete

Asymptotics with mutations



$$\begin{cases} \varepsilon \frac{\partial}{\partial t} n_\varepsilon(t, x) - \varepsilon^2 \Delta n_\varepsilon = n_\varepsilon(t, x) R(x, \varrho_\varepsilon(t)), \\ \varrho_\varepsilon(t) = \int_{\mathbb{R}^d} n_\varepsilon(t, x) dx. \end{cases}$$

In the limit one can expect

$$0 = n(t, x) R(x, \varrho(t)),$$

$$n(t, x) = \rho \delta_{\Gamma(t)}, \quad \Gamma(t) \subset \{R(\cdot, \rho(t)) = 0\}.$$

Asymptotics with mutations



$$\begin{cases} \varepsilon \frac{\partial}{\partial t} n_\varepsilon(t, x) - \varepsilon^2 \Delta n_\varepsilon = n_\varepsilon(t, x) R(x, \varrho_\varepsilon(t)), \\ \varrho_\varepsilon(t) = \int_{\mathbb{R}^d} n_\varepsilon(t, x) dx. \end{cases}$$

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Which points are selected in this hypersurface ?

Asymptotics with mutations

$$\begin{cases} \varepsilon \frac{\partial}{\partial t} n_\varepsilon(t, x) - \varepsilon^2 \Delta n_\varepsilon = n_\varepsilon(t, x) R(x, \varrho_\varepsilon(t)), \\ \varrho_\varepsilon(t) = \int_{\mathbb{R}^d} n_\varepsilon(t, x) dx. \end{cases}$$

In the limit one can expect

$$0 = n(t, x) R(x, \bar{\varrho}(t)),$$

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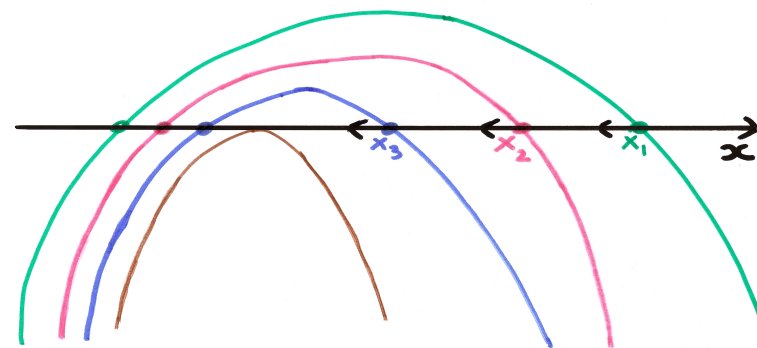
In dimension $d = 1$, R monotone, there is a single point.

$$\bar{x}(t) \iff \bar{\varrho}(t)$$

Concentration phenomena, $d \geq 1$

$$\begin{cases} \varepsilon \frac{\partial}{\partial t} n_\varepsilon(x, t) - \varepsilon^2 \Delta n_\varepsilon = n_\varepsilon(x, t) R(x, \varrho_\varepsilon(t)), & x \in \mathbb{R}^d \\ \varrho_\varepsilon(t) = \int_{\mathbb{R}^d} n_\varepsilon(x, t) dx. \end{cases}$$

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Theorem (Any d , concave.) For well-prepared initial data, we have

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$$R(\bar{x}(t), \bar{\varrho}(t)) = 0 \quad \text{for all } t > 0$$

$$\text{as } t \rightarrow \infty \quad R(\bar{x}_\infty, \bar{\varrho}_\infty) = 0 = \min_\varrho \max_x R(x, \varrho)$$

Proof

Step 1. $\varrho_\varepsilon(t) \in_b L^\infty$, $n_\varepsilon \in_b L_t^\infty(L_x^1)$

Step 2. A BV estimate

Step 3. Represent

$$n_\varepsilon(t, x) = \exp \frac{\varphi_\varepsilon(t, x)}{\varepsilon}$$

the 'fittest' trait $\bar{x}(t)$ is characterised by the **Eikonal equation with constraints**

$$\left\{ \begin{array}{l} \frac{\partial}{\partial t} \varphi(t, x) = R(x, \bar{\varrho}(t)) + |\nabla \varphi(t, x)|^2 \\ \max_x \varphi(t, x) = 0 \quad \left(= \varphi(t, \bar{x}(t)) \right) \end{array} \right.$$

Proof

In the viscosity sense

$$\begin{cases} \frac{\partial}{\partial t} \varphi(t, x) = R(x, \bar{\varrho}(t)) + |\nabla \varphi(t, x)|^2 \\ \max_x \varphi(t, x) = 0 \quad \left(= \varphi(t, \bar{x}(t)) \right). \end{cases}$$

$\varphi(t, x)$ is Lipschitz

This is not an obstacle problem.

$\bar{\varrho}(t)$ is a Lagrange multiplier !

Proof

In the viscosity sense

$$\begin{cases} \frac{\partial}{\partial t} \varphi(t, x) = R(x, \bar{\varrho}(t)) + |\nabla \varphi(t, x)|^2 \\ \max_x \varphi(t, x) = 0 \quad \left(= \varphi(t, \bar{x}(t)) \right). \end{cases}$$

Uniqueness

- $R(x, \varrho) = b(x)a(\varrho) - d(x)$ (G. Barles and BP)
- J.-M. Roquejoffre et S. Mirrahimi
- V. Calvez, A. Lam Work in preparation

Proof

$$\begin{cases} \frac{\partial}{\partial t} \varphi(t, x) = R(x, \bar{\rho}(t)) + |\nabla \varphi(t, x)|^2 \\ \max_x \varphi(t, x) = 0 \quad \left(= \varphi(t, \bar{x}(t)) \right). \end{cases}$$

Step 4. Any concentration point $x_i(t)$ will satisfy

$$R(\bar{x}_i(t), \bar{I}(t)) = 0$$

Thanks to semi-concavity property of $\varphi(t, x)$

$$-\nu Id \leq D^2 \varphi.$$



Canonical equation

Step 5. The concave case leaves place for a regularity regime, if

$$D^2R \leq -\nu Id, \quad D^2\varphi^0 \leq -\nu Id,$$

then

$$D^2\varphi \leq -\nu Id.$$

Canonical equation

Any concentration point $x_i(t)$ will satisfy

$$(i) \quad R(\bar{x}_i(t), \bar{I}(t)) = 0$$

$$(ii) \quad \frac{d}{dt}\bar{x}_i(t) = \left(-D^2\varphi(\bar{x}_i(t), t) \right)^{-1} \cdot \nabla R(\bar{x}_i(t), \bar{I}(t))$$

Canonical equation

Any concentration point $x_i(t)$ will satisfy

$$(i) \quad R(\bar{x}_i(t), \bar{I}(t)) = 0$$

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Conclusions :

- The competitive exclusion principle (single Dirac mass for a single nutrient)

For two nutrients $R(\bar{x}_i(t), \bar{I}_1(t), I_2(t)) = 0$

one has four unknowns $\bar{I}_1(t), I_2(t), \bar{x}_1(t), x_2(t)$

$R(x, I_1, I_2)$ should have 1 or 2 roots (Champagnat, Jabin, Méléard)

Canonical equation

Any concentration point $x_i(t)$ will satisfy

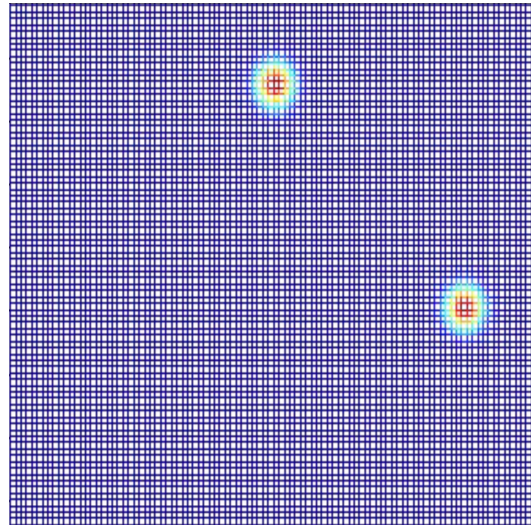
$$(i) \quad R(\bar{x}_i(t), \bar{I}(t)) = 0$$

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Conclusions :

- The competitive exclusion principle (single Dirac mass)
- $n_\varepsilon = \exp(\varphi/\varepsilon)$ the shape of φ plays a role

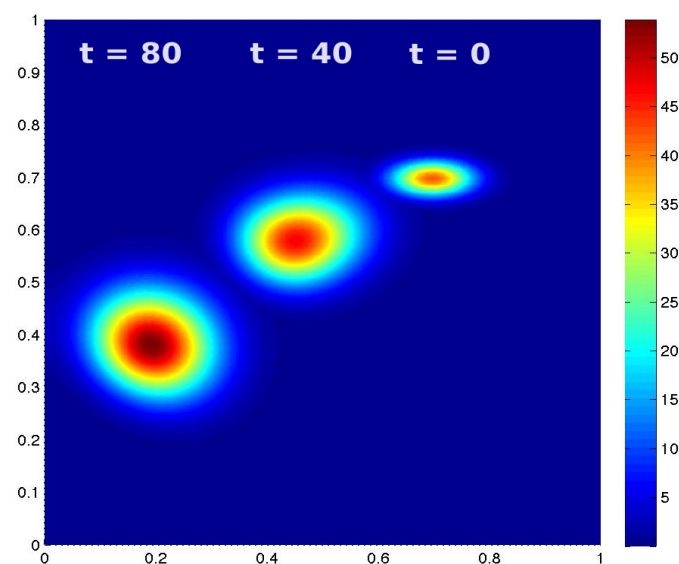
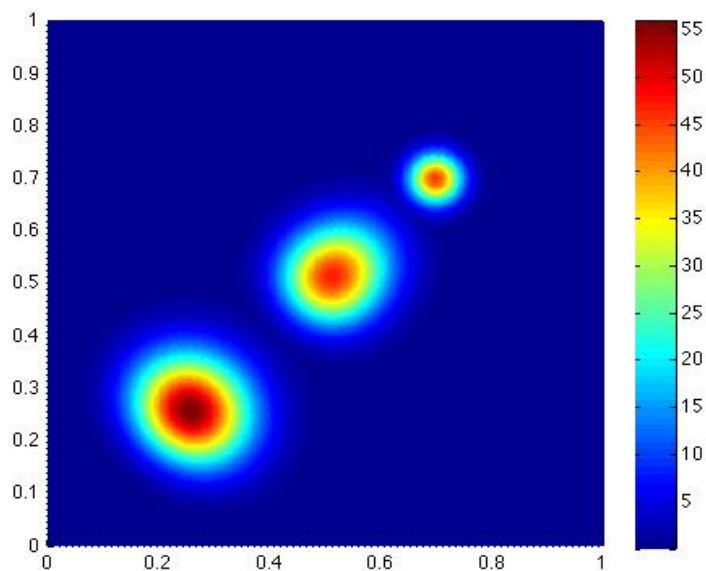
Canonical equation



Canonical equation

$$\frac{d}{dt}\bar{x}(t) = \left(-D^2\varphi(\bar{x}(t), t) \right)^{-1} \cdot \nabla R(\bar{x}(t), \bar{q}(t))$$

Effect of the matrix $\left(-D^2\varphi(\bar{x}(t), t) \right)$ (microstructure of the Dirac)



Challenges today



- Explain diversity/heterogeneity with space
- Selection without a proliferating advantage



Challenges today

- Explain diversity/heterogeneity with space
- Selection without a proliferating advantage

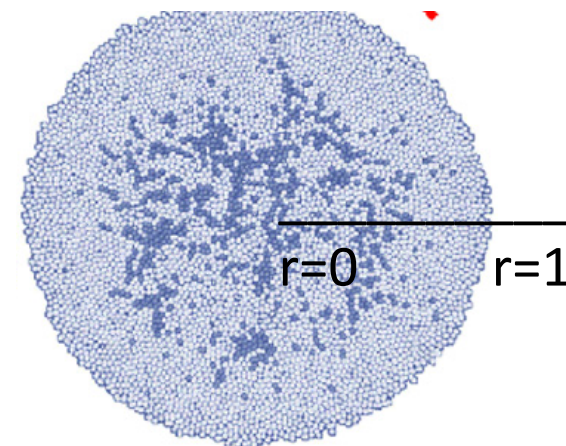
Examples are

- Local selection of a trait with a space variable
- Selection of the fittest age/size
- Selection of dispersal

Space-trait concentration

Let $y \in \mathbb{R}$ the space variable, $x \in \mathbb{R}$ trait variable

$$\begin{cases} \varepsilon \partial_t n_\varepsilon(y, x, t) = [r(x)c_\varepsilon(y, t) - d(x)\varrho_\varepsilon(y, t) - \mu(x)] n_\varepsilon(y, x, t) \\ -\Delta_y c_\varepsilon(y, t) + [\varrho_\varepsilon(y, t) + \lambda] c_\varepsilon(y, t) = \lambda c_B, \\ \varrho_\varepsilon(y, t) = \int n_\varepsilon(y, x, t) dx \end{cases}$$



Interpretation

- Nutrients/drugs are diffused and consumed by cells
- Local conditions select space-dependent traits

Space-trait concentration

Let $y \in \mathbb{R}$ the space variable, $x \in \mathbb{R}$ trait variable

$$\begin{cases} \varepsilon \partial_t n_\varepsilon(y, x, t) = [r(x)c_\varepsilon(y, t) - d(x)\varrho_\varepsilon(y, t) - \mu(x)] n_\varepsilon(y, x, t) \\ -\Delta_y c_\varepsilon(y, t) + [\varrho_\varepsilon(y, t) + \lambda] c_\varepsilon(y, t) = \lambda c_B, \\ \varrho_\varepsilon(y, t) = \int n_\varepsilon(y, x, t) dx \end{cases}$$

Theorem : For well-prepared initial data, as $\varepsilon_k \rightarrow 0$, we have

$$n_\varepsilon(y, x, t) \rightarrow \bar{\rho}(y, t) \delta(x - \bar{X}(y, t))$$

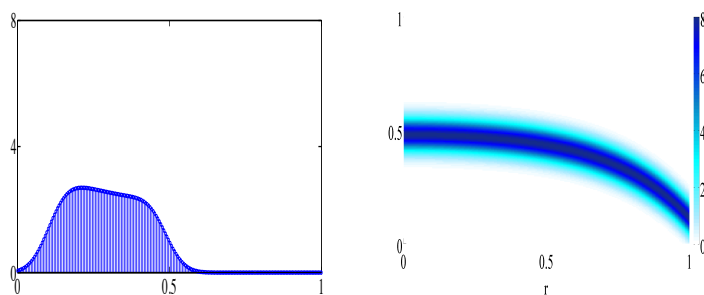
Difficulty : Space works well with L^∞ . Traits with L^1

Outcome : Explains heterogeneity

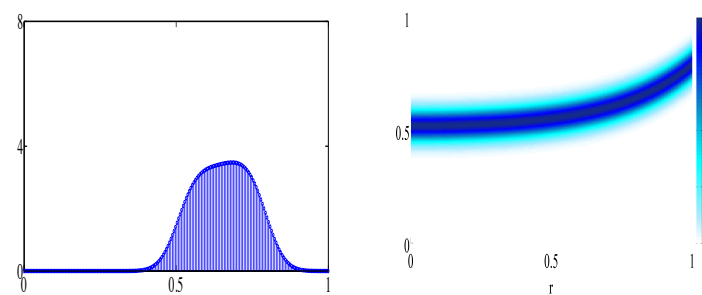
Space-trait concentration

Let $y \in \mathbb{R}$ the space variable, $x \in \mathbb{R}$ trait variable

$$\begin{cases} \varepsilon \partial_t n_\varepsilon(y, x, t) = [r(x)c_\varepsilon(y, t) - d(x)\varrho_\varepsilon(y, t) - \mu(x)] n_\varepsilon(y, x, t) \\ -\Delta_y c_\varepsilon(y, t) + [\varrho_\varepsilon(y, t) + \lambda] c_\varepsilon(y, t) = \lambda c_B, \\ \varrho_\varepsilon(y, t) = \int n_\varepsilon(y, x, t) dx \end{cases}$$



Without cytotoxic drug
High heterogeneity



With cytotoxic drug
Lower heterogeneity

Selection of age

A second example (viral load, age when cancer occurs)

$$\begin{cases} \varepsilon \partial_t n_\varepsilon(y, x, t) + \partial_y [A(x, y) n_\varepsilon(y, x, t)] + [d(x, y) + \rho_\varepsilon(t)] n_\varepsilon(y, x, t) = 0 \\ A(x, y = 0) n_\varepsilon(y = 0, x, t) = \int b(x, y') M_\varepsilon(y, y') n_\varepsilon(y', x, t) dy' dx \\ \rho_\varepsilon(t) = \int_{y=0}^{\infty} \int_x n_\varepsilon(y, x, t) dx dy \end{cases}$$

How to describe the concentration effect ?

Selection of age

Consider the eigenvalue problem x by x

$$\begin{cases} \partial_y [A(x, y)N(y, x)] + d(x, y)N(y, x) = \Lambda(x, \eta) \\ A(x, y = 0)N(y = 0, x) = \eta \int b(x, y)N(y, x)dydx \\ N(y, x) > 0 \end{cases}$$

The dynamics of concentration is described by

$$\begin{cases} \partial_t \varphi(x, t) + \bar{\rho}(t) + \Lambda(x, \int M(z)e^{z \cdot \nabla \varphi(x, t)} dz) = 0 \\ \max_x \varphi(x, t) = 0. \end{cases}$$

Selection of age



$$\begin{aligned}n_\varepsilon(y, x, t) &\approx \bar{\rho}(t) e^{\varphi_\varepsilon(x, t)/\varepsilon} N_\varepsilon(x, y, t) \\ &\approx \bar{\rho}(t) \delta(x - \bar{x}(t)) N(y, t)\end{aligned}$$

The strategy of proof is to use $\varphi_\varepsilon(x, t)$ and handle the other corrections by entropy methods for $N_\varepsilon(x, y, t)$

Selection of age

$$\begin{aligned}
 n_\varepsilon(y, x, t) &\approx \bar{\rho}(t) e^{\varphi_\varepsilon(x, t)/\varepsilon} N_\varepsilon(y, x, t) \\
 &\approx \bar{\rho}(t) \delta(x - \bar{x}(t)) N(y, t)
 \end{aligned}$$

The canonical equation is

$$\frac{d}{dt} \bar{x}(t) = \left(-D^2 \varphi(\bar{x}(t), t) \right)^{-1} \left[\nabla_x \Lambda(x, 1) + \frac{\partial \Lambda(x, 1)}{\partial \eta} D^2 \varphi(\bar{x}(t), t) \cdot M_1 \right]$$

$$M_1 = \int z M(z) dz$$

$M_1 = 0$ for symmetric mutation kernels



Evolution of dispersal

Selection without a proliferative advantage ?

- motility/dispersal of individuals is subject to variability
- no advantage regarding their reproductive rate
- $R(x, \rho) =$ Operator acting on the space variable

Hastings, *Theor. Popul. Biol.* 1983



Evolution of dispersal

We model it for $y \in \Omega$ + Neuman BC, $x =$ dispersal (trait)

$$\partial_t n(t, x, y) = \underbrace{D(x) \partial_{yy}^2 n(t, x, y)}_{\text{dispersion/motility}} + \underbrace{n(t, x, y) (K(y) - \rho(t, y))}_{\text{reproduction}} + \underbrace{\varepsilon^2 \partial_{xx}^2 n(t, x, y)}_{\text{mutations on motility}}$$

$\underbrace{\hspace{15em}}_{=R(x, \cdot)}$

$$\rho(t, y) = \int_0^\infty n(t, x, y) dx$$

$K(y)$ is not constant.



Evolution of dispersal

$$\partial_t n(t, x, y) = \underbrace{D(x) \partial_{yy}^2 n(t, x, y)}_{\text{dispersion/motility}} + \underbrace{n(t, x, y) (K(y) - \rho(t, y))}_{\text{reproduction}} + \underbrace{\varepsilon^2 \partial_{xx}^2 n(t, x, y)}_{\text{mutations on motility}}$$

$$\rho(t, y) = \int_0^\infty n(t, x, y) dy$$

Theorem (P. E. Souganidis, BP and K. Y. Lam, Y. Lou) The ESS are of the form

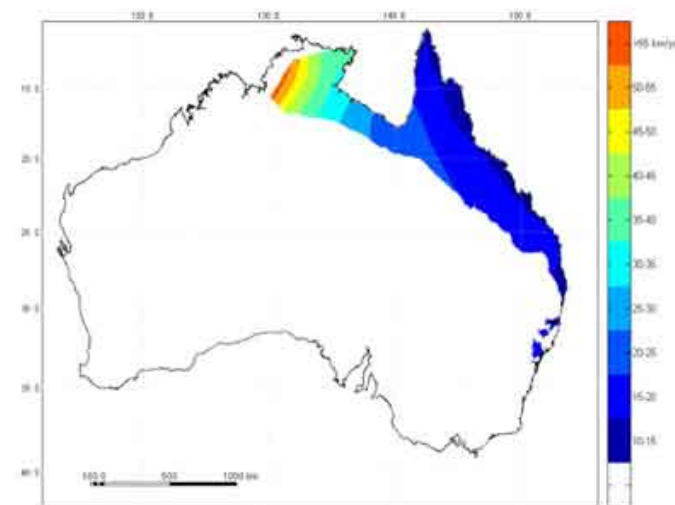
$$n(t, x, y) \approx \bar{\rho}_\infty(y) \delta(x = \bar{x}), \quad D(\bar{x}) = \min D(x)$$

and the constrained H.-J. eq.

$$\begin{cases} \frac{\partial}{\partial t} \varphi(x, t) = \Lambda(x, \bar{\rho}(\cdot, t)) + |\nabla \varphi|^2 \\ \max_x \varphi(x, t) = 0 = \varphi(\bar{x}(t), t), \end{cases}$$

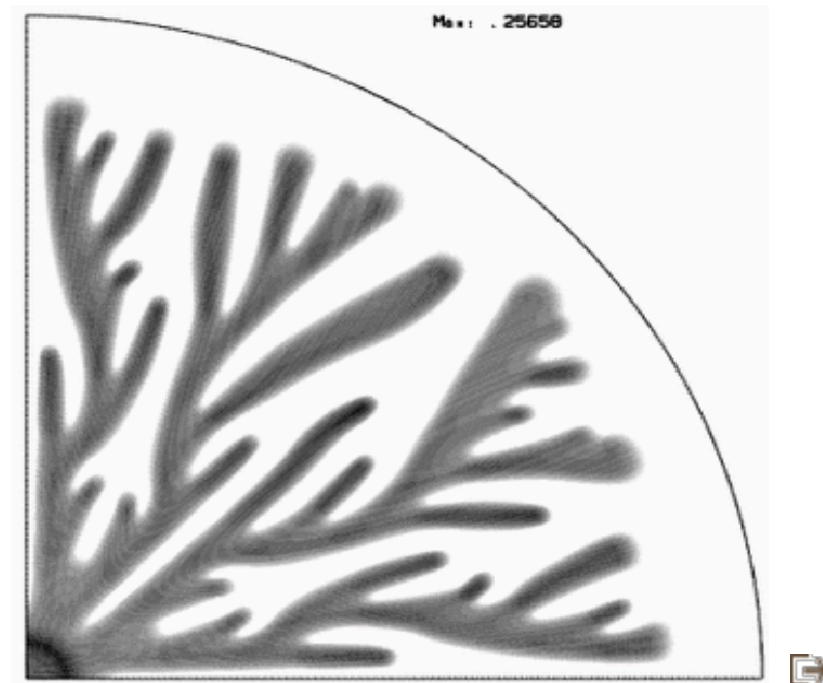
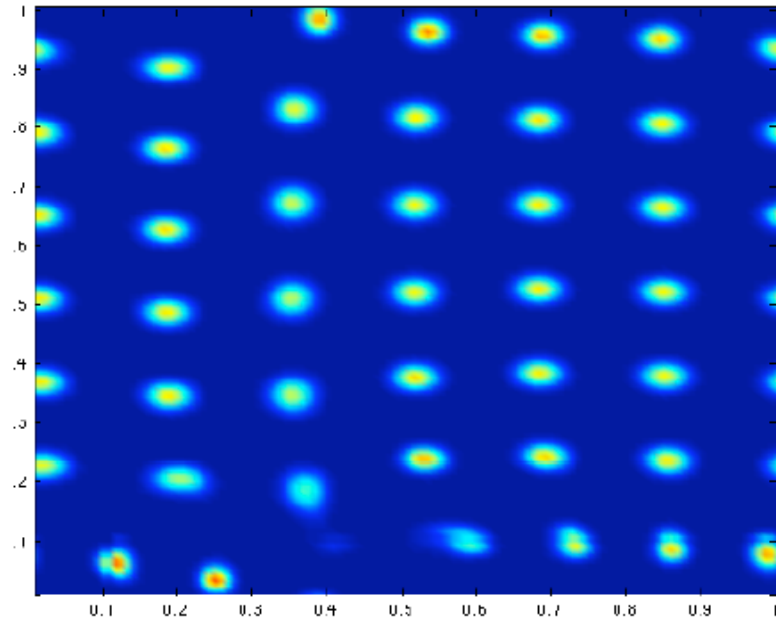
Evolution of dispersal

- Same question for traveling waves
- Accelerating waves
- Example cane toads invasion in Australia



J. Berestycki, E. Bouin, V. Calvez, C. Mouhot, G. Raoul, L. Ryzhik., C. Henderson

Turing (dendritic) patterns



Thanks to my collaborators

O. Diekmann, P.-E. Jabin, S. Mischler,
M. Gauduchon, J. Clairambault, A. Escargueil,
G. Barles, S. Mirrahimi, P. E. Souganidis,
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Happy birthday Mete